# UNIVERSITY OF WISCONSIN – STOUT CAPSTONE VIRACON - TILT TABLE

TEAM 11 – NATE KARAU, SOPHIE GELHAR, BRANDON HAAG, JORDAN OTT, AND ALEX SUELFLOW



# INTRODUCTION



#### Who is Viracon



V I R A C O N®

Located in Owatonna, MN

Architectural glass fabricator that adds coating to glass panels for exterior use

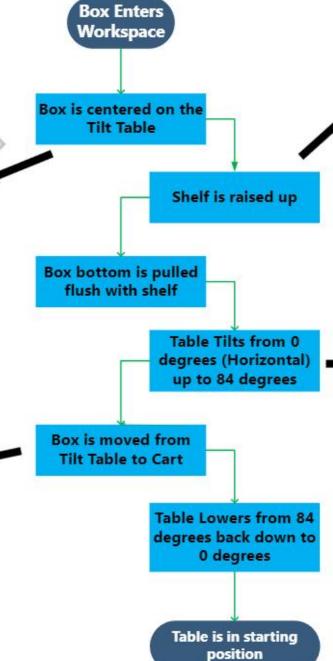
Name comes from "Environmental Control"

Create glass panes of different varieties, including laminated and insulated glass

Also applies coatings to modify thermal insulation capabilities.

Projects are all custom ordered so the sizes of the pieces and packaging vary.





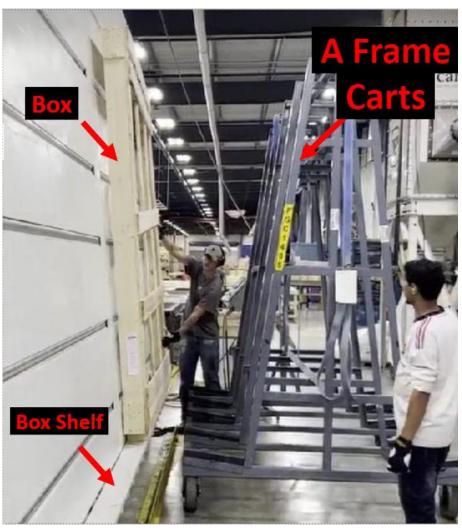




**Tilt Table Process Flow** 

This Process Flow covers the step by step that a box undergoes from entering the Tilt Table workspace from the build table to leaving the cart loading zone on a cart.

#### The Problem



- Wooden frames where glass is packaged and shipped are called "Boxes" and weigh up to 400lbs.
- Current transition of boxes from tilt table to A frame carts is by lifting boxes by 2 people, which poses many ergonomic issues.
- Boxes tend to tip off Box Shelf when Table is fully vertical due to boxes center of gravity being beyond the Shelf.
- Our goal is to re-design this table to make transitioning the Boxes safer and more reliable.

# PROJECT SCOPE



#### **Creating Scope of Work**

Due to the importance of the scope of work there are multiple steps to the process

- Seeing Process in Person
- Speaking with Sponsors to Understand Project
- Presenting Draft of Scope of Work to Professors

#### Scope of Work

The scope of work is to prototype a 1/3 scale alteration to the tilt table that serves as a proof of concept for loading boxes onto the cart with an automated system.



# **DESIGN CONCEPTS**



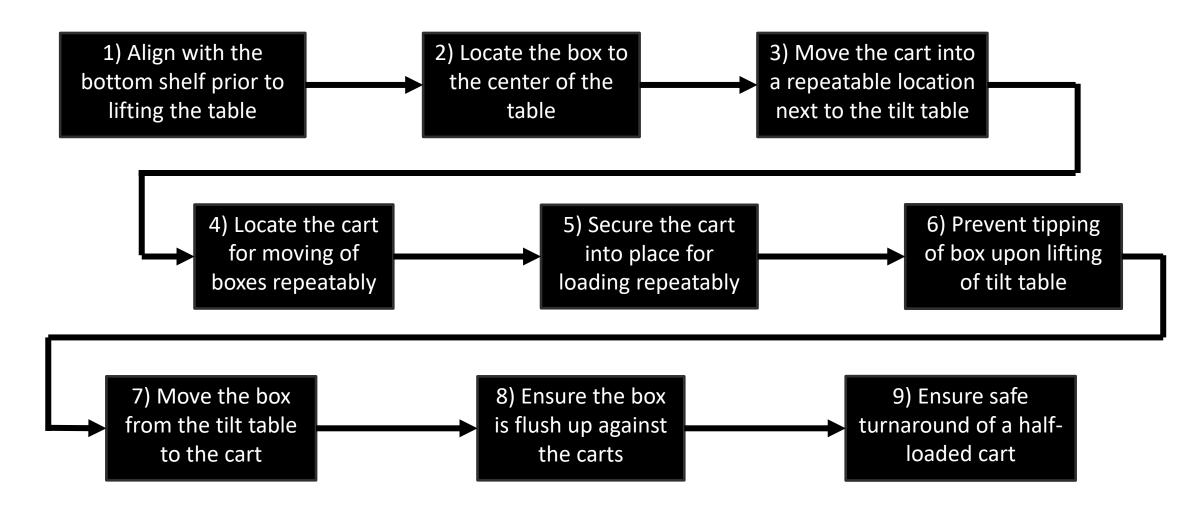
#### **Determining Functional Needs**

Before beginning the design, we needed to determine the functional needs for our prototype. This is done by:

- Discussing with our sponsors what their expectations were for the solution.
- Developing the process flow to understand the steps currently taking place.

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#### **Functional Need Process Map**



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#### **Concept Generation**

	Morphological Matrix						
Functional Need Concept 1 Concept		Concept 2	Concept 3	Concept 4	Concept 5		
	Prevent tipping of box upon lifting of tilt table	clamping bar  Day 1 sees here  long cross his to	Brace bar	Pinch bars  Adjustable Borders  Forting to the state of t	Lengthen box shelf	Suctioning feature to hold it in place	
	The box is moved from the tilt table to the cart	Slide Box onto cart	Lower box with pistons	Roll onto cart	Crane	Push bar Pistons, when table turned 90 degrees	
	Ensuring the box is flush up against the carts	Extending pistons to push into place	Push table angle past 90 degrees to line up the angles	Magnets on cart connect with magnets on box	Horizontal tightening straps, add brackets to side of cart to prevent slippage    Horizontal Tightening   Strapt   Strap	straps or chains across the box to sinch into place	

#### **Concept Generation**

Ensuring the box is flush up against the carts

# Extending pistons to push into place

#### **Concept Evaluation**

CRITERIA	WEIGHTAGE
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%
Necessary Manpower (<5 requires more input, >5 less human input)	12%
Cycle Time (<5 Time loss, >5 time improvement)	15%
Predicted Accuracy (1-10 as 50%-100%)	20%
Safety of function (1-10)	23%
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%

#### **Concept Evaluation**



varying sized 2 step Push bar pistons when side loading

RATING TOTAL

4.13%

11.70%

10.50%

15.50%

18.98%

12.00%

2.75

9.75

7

7.75

8.25

8

CRITERIA - W

Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)

Necessary Manpower (<5 requires more input, >5 less human input)

Cycle Time (<5 Time loss, >5 time improvement)

Predicted Accuracy (1-10 as 50%-100%)

Safety of function (1-10)

Complexity to impliment (1-10) 1 being very difficult, 10 being simple

WEIGHTAGE				
	Brandon	Sophie	Nate	Alex
15%	3	4	2	2
12%	10	10	10	9
15%	9	6	7	6
20%	9	8	7	7
23%	8	8	9	8
15%	8	9	8	7

Description (Optional): Using tall vertical bars

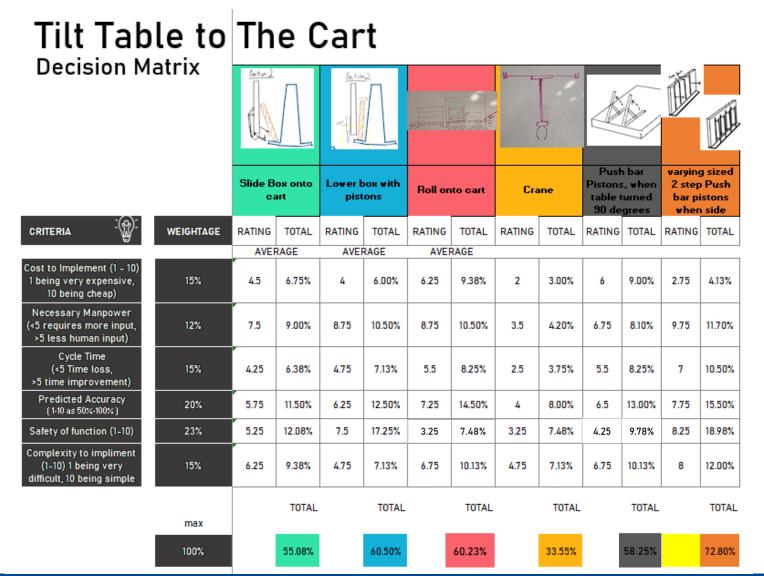
the table onto the cart

actuated by pistons to push the box frame out from

TOTAL

72.80%

#### **Concept Evaluation**



# PREDICTIVE ANALYSIS

#### **Defining Predictive Analysis Process:**

Ask questions that justify concepts we just evaluated:

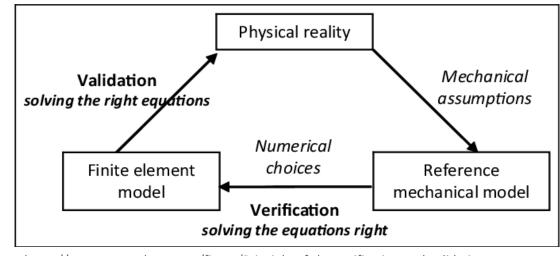
 The justification will prove that the concept works and how we designed using engineering analysis methods

The questions must be answered with at least 2 analysis methods:

- 1. Experiment
- 2. Hand calculations
- 3. Finite element analysis

Once Done, ensure data is both:

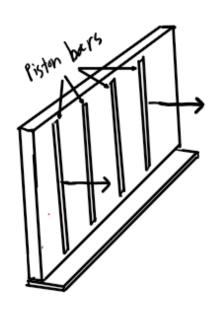
- Verified: Is the math done correctly?
- Validated: Do the results make sense?

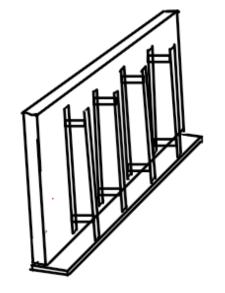


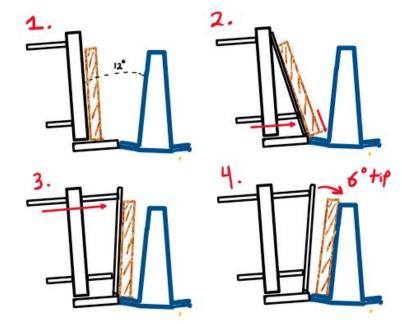
 $\frac{https://www.researchgate.net/figure/Principle-of-the-verification-and-validation-methodology\ fig1\ 258186808$ 

#### Predictive Analysis Question Example

Engineering Questions	Method to Solve	Resources Needed for Method	Method to Benchmark	Resources Needed for Method	How Results Will Further Design	Functional Need
How far do the top/bottom pistons need to each extend to push the box flush to the back of the cart?	Experiment	Sizes of the cart, table, and box.	Physical experimentatio n	Wooden blocks matching scaled down sized of box, table, and cart	This will help us determine the furthest distance necessary that pistons need to extend and piston size.	Box flush up against the carts







#### Hand Calculations – Push Piston Concept Ex.

#### – Knowns:

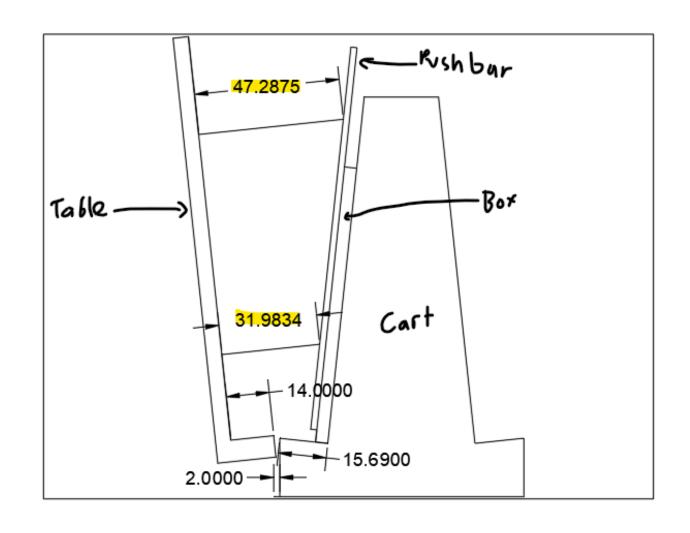
- Angle of box shelf and cart shelf: 6 deg
- Angle of tilted table and cart: 6 deg
- Position of bar vertically on the table: 4in up, 8in down
- Length of box shelf: 14in
- Depth of deepest cart: 15.69in
- Depth of shallowest box: 4in
- Height of tilt table: 137in

#### – Assumed values:

- Distance between shelf and cart: 2in
- Vertical positions of pistons: 24in in from edges
- Depth of push bar = 2in

#### Solved Values with AutoCAD:

- Max extension for bottom piston: 31.984in
- Max extension for top piston: 47.2875in



#### Prototype – Push Piston Concept Ex.

Functional
Lego model
as a physical
proof of
concept
display



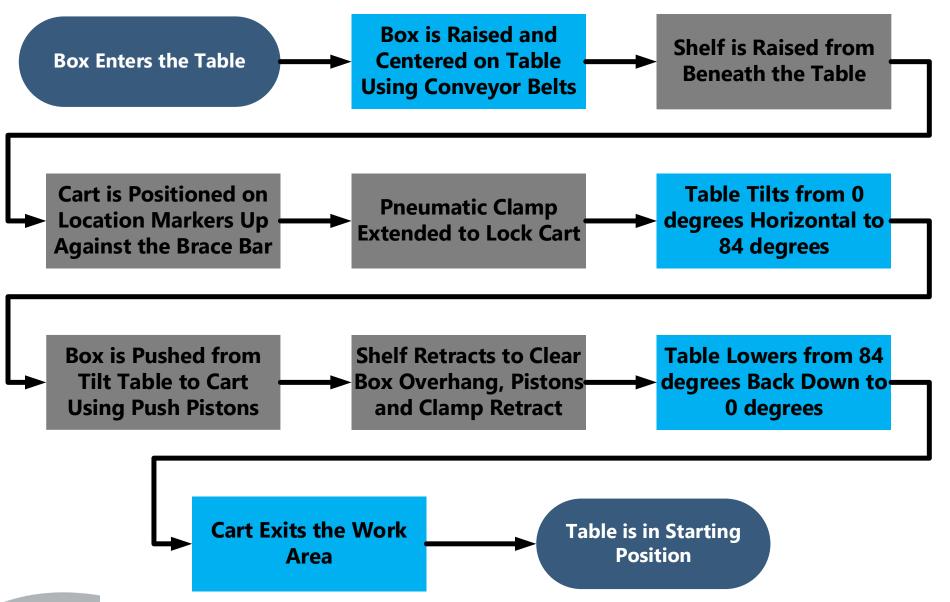
video-20231116-172629-8ebf69fa.mov

# COMPLETE DESIGN REVIEW – PART 1

#### **Complete Design Review**

#### During this time, we

- Cleaned up documentation
- Finished the initial 3D model
- Created justification for all processes



Redesign Process Flow

Note: Gray indicates processes that changed in Semester 2

#### **Box Enters the Table**

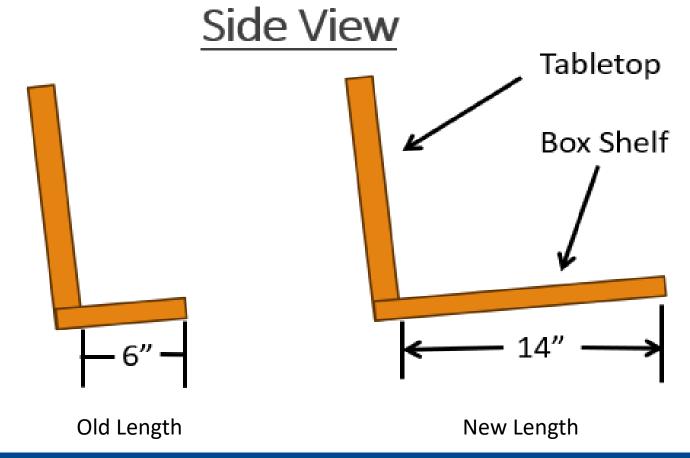
#### Box is Raised and Centered on Table Using Conveyor Belts



Painted green square indicates where box should be to be centered.

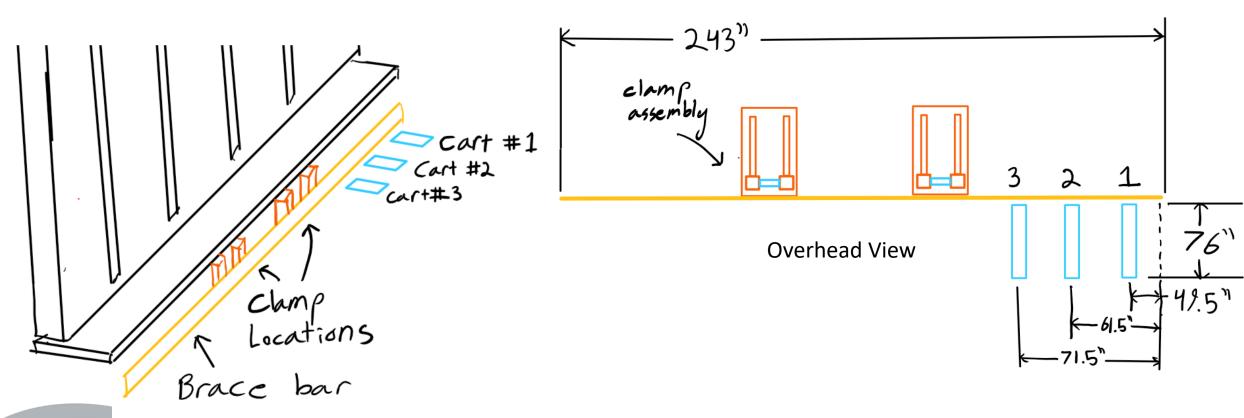




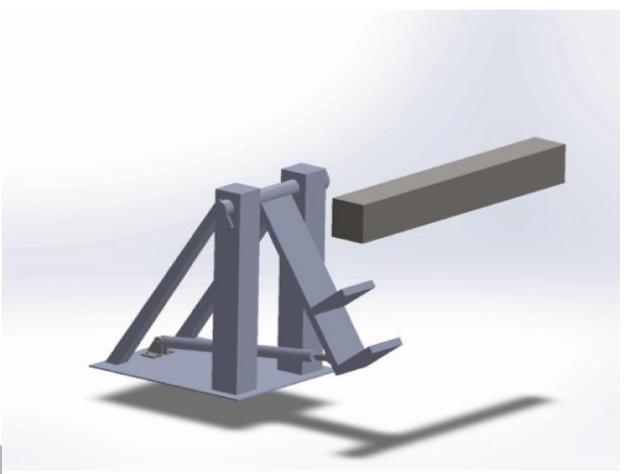








# Pneumatic Clamp Extended to Lock Cart



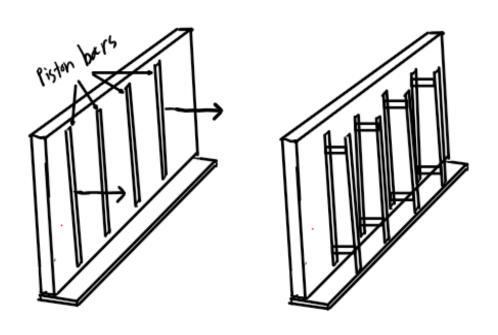
Clamp lifts to attach to bar on cart, securing it in place.

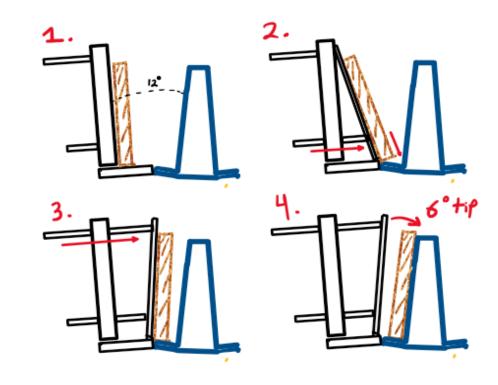


# Table Tilts from 0 degrees Horizontal to 84 degrees

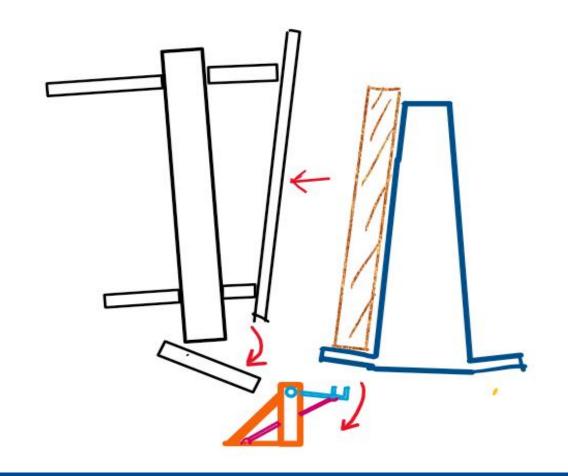


# Box is Pushed from Tilt Table to Cart Using Push Pistons









# Table Lowers from 84 ► degrees Back Down to 0 degrees

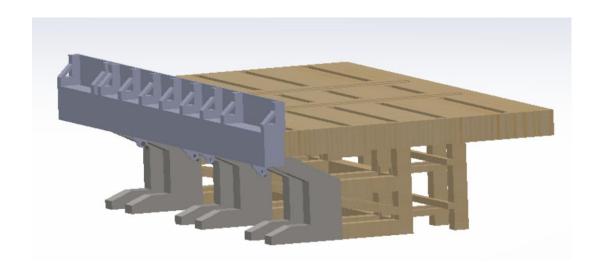


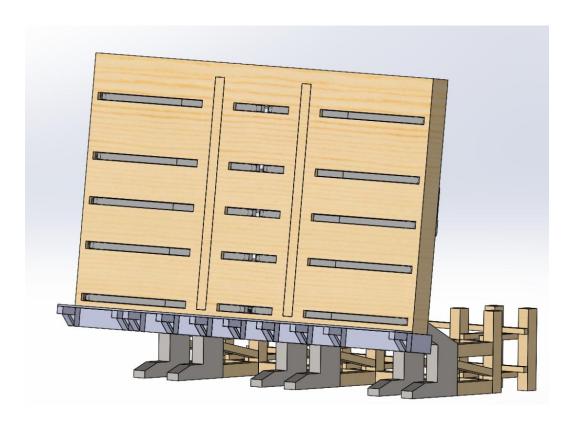
# Cart Exits the Work Area

## Table is in Starting Position



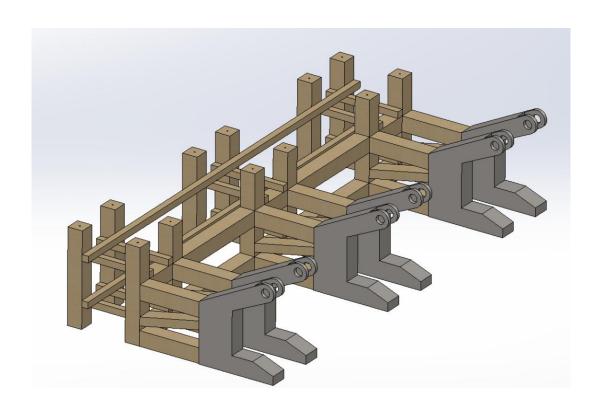


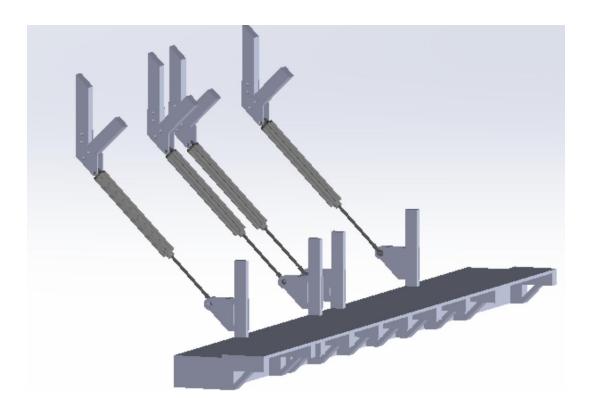




## FULL MODEL







### FULL MODEL



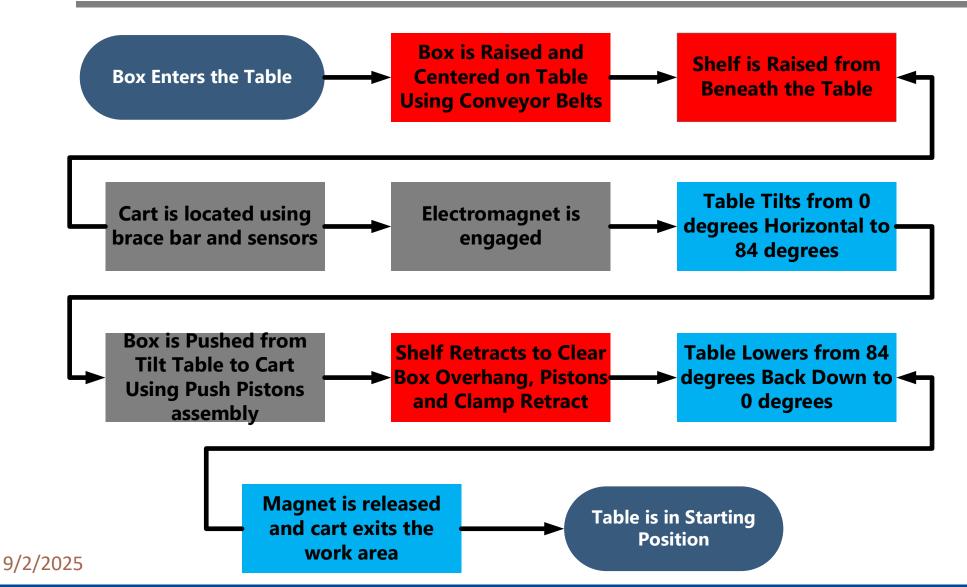
# COMPLETE DESIGN REVIEW – PART 2

# Re-defining Scope

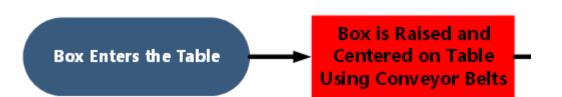
- Through comments from professors in previous presentations
- Another site visit with Viracon
- New team member perspective

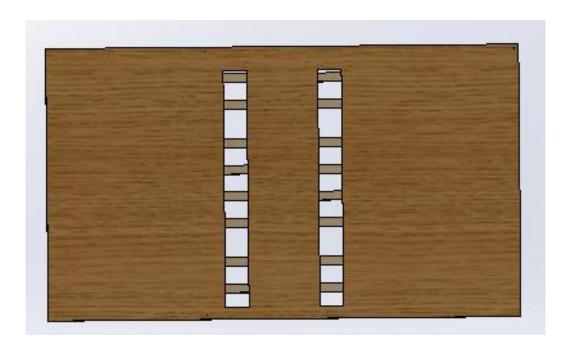
We realized we were doing a lot of work outside the project goals. So, we modified our scope to better reflect those goals

### **Process Flow**

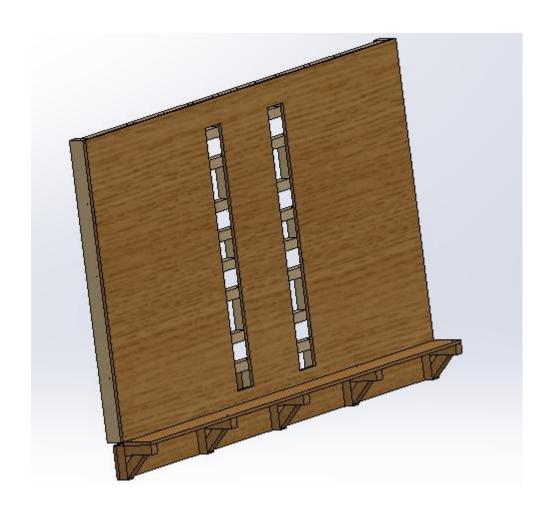


Note: Red indicates processes that were removed from our system in semester 2





Shelf is Raised from Beneath the Table

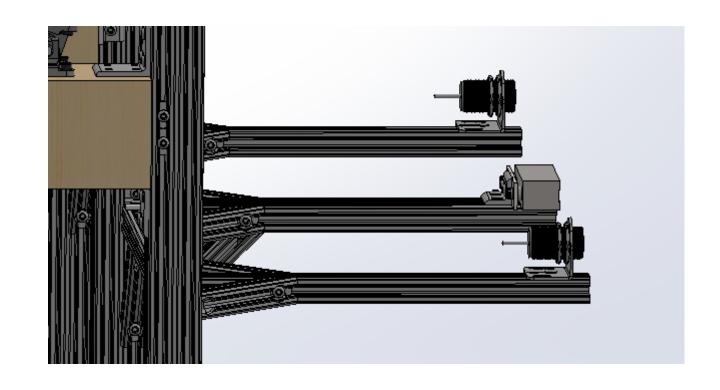


Cart is located using brace bar and sensors



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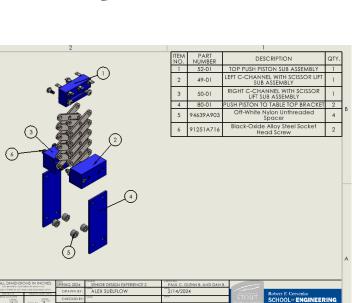
Electromagnet is engaged

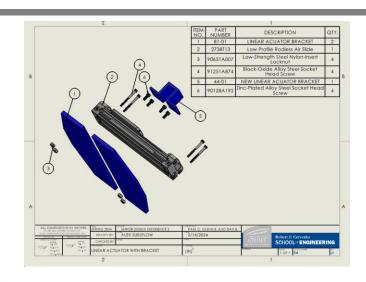


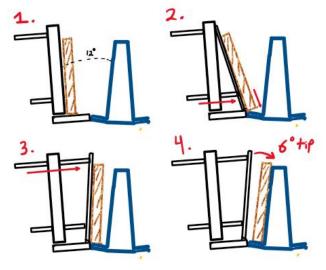
# Table Tilts from 0 degrees Horizontal to 84 degrees



Box is Pushed from Tilt Table to Cart Using Push Pistons assembly

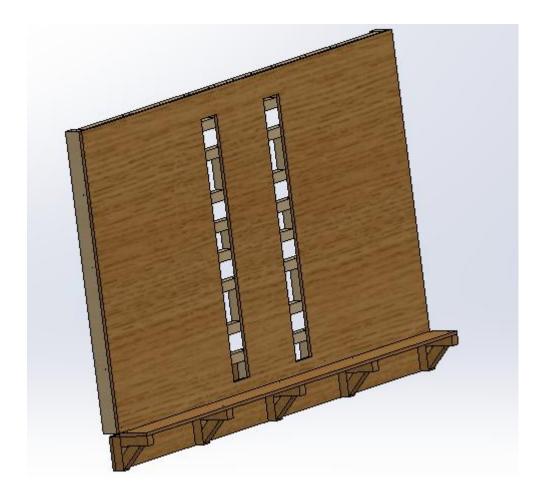






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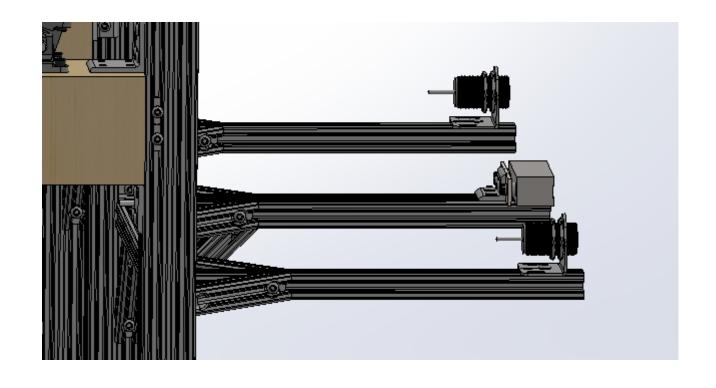
Shelf Retracts to Clear
► Box Overhang, Pistons—
and Clamp Retract



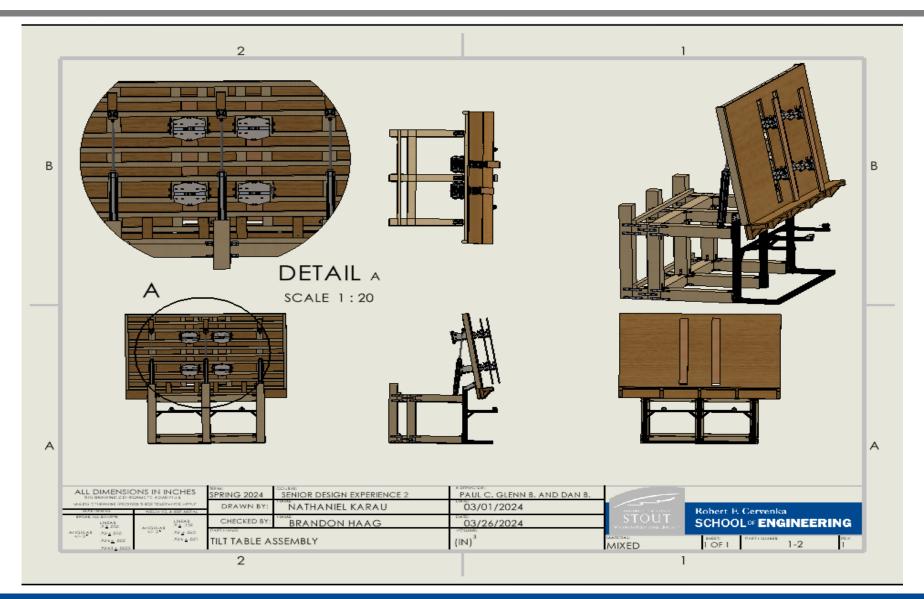
# Table Lowers from 84 degrees Back Down to 0 degrees



Magnet is released
- and cart exits the
work area



### Updated Model Part 2



# **CONTROLS**



### Complete Design Review: Controls

### **INPUTS**

HMI PB1 – Table Extend

HMI PB2 – Table Retract

HMI PB3 – Bottom Push Pistons Extend

HMI PB4 – Top Push Pistons Retract

HMI PB5 – Push Pistons Retract

HMI PB6 – Rest

HMI PB7 Magnet

PB8 – E-Stop

PROX 1

PROX 2

#### **OUTPUTS**

Sol1 – Extend Bottom Push Piston

Sol2 – Retract Bottom Push Piston

Sol3 – Extend Top Push Piston

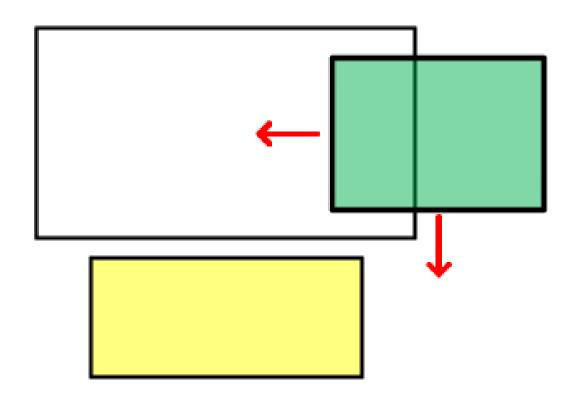
Sol4 – Retract Top Push Piston

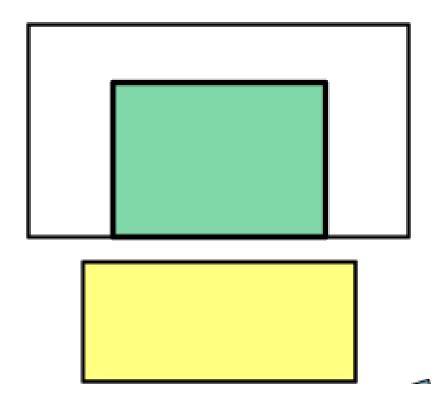
Sol5 – Extend Tilt Table

Sol6 – Retract Tilt Table

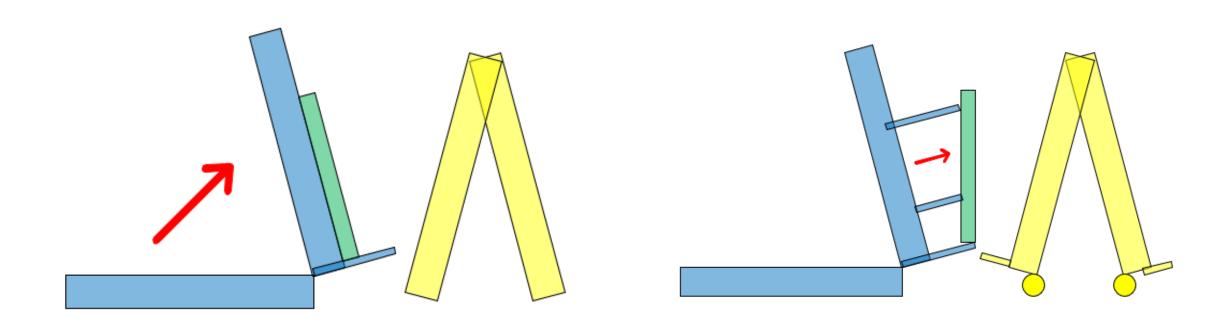
Magnet

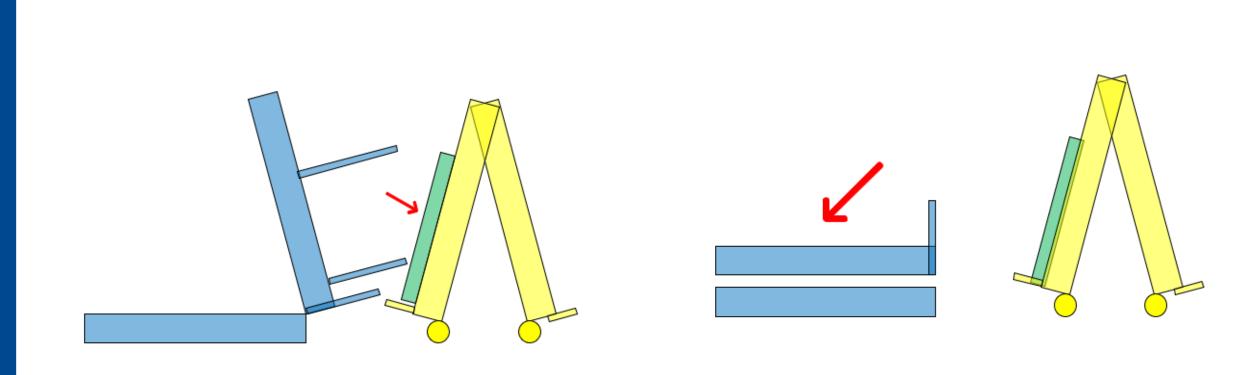
### **Controls: Part Flow**



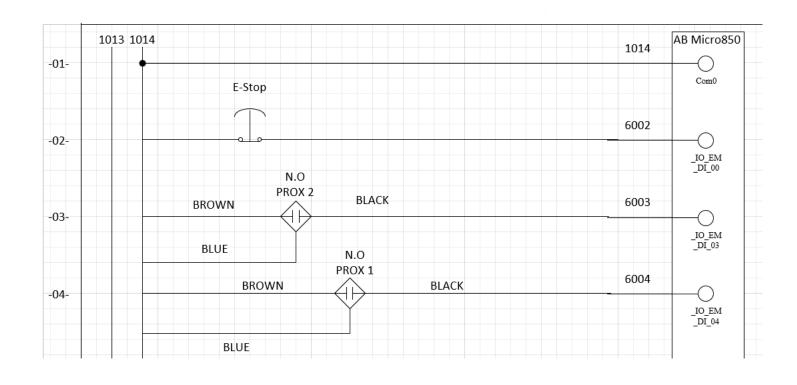


### **Controls: Part Flow**

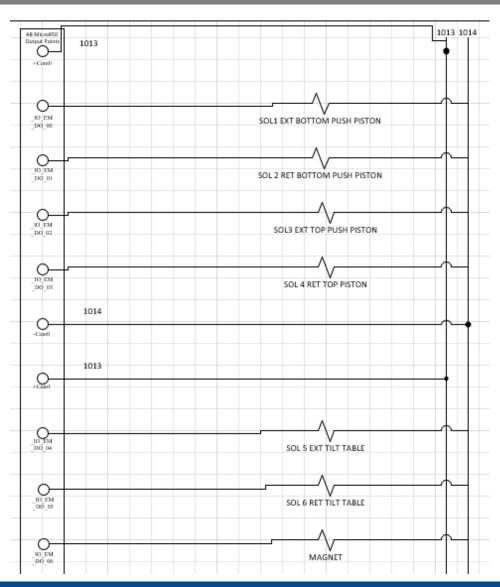




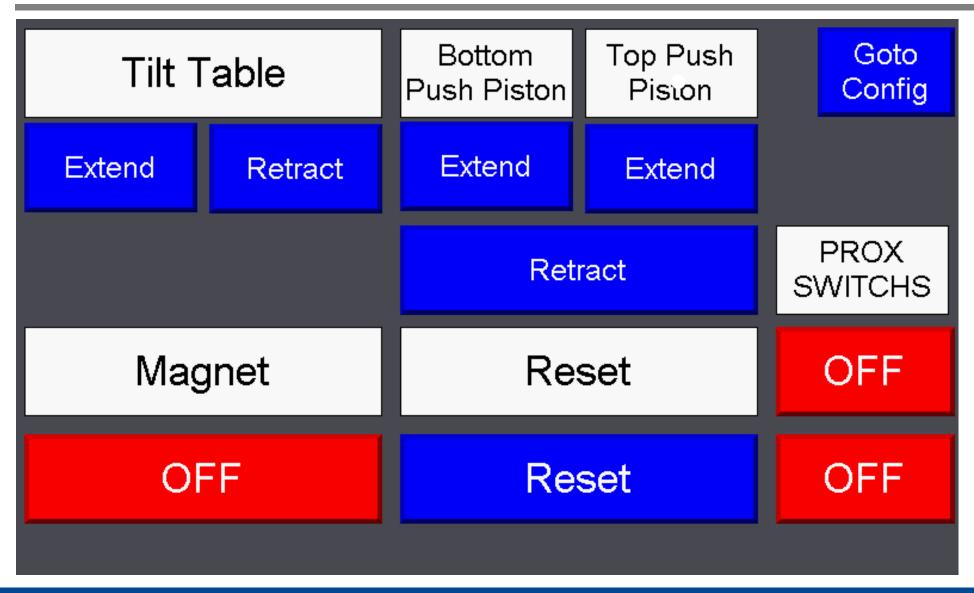
### **INPUTS**



### **OUTPUTS**



### HMI



# FINAL BUILD

### Parts list

### We organized the parts in this excel

Assem. #	Part #	Rev.	Name	CAD Drawing	QTY for Build	Dimension (LxHxW) INCH	Vendor	Cost	PKG QTY	Total Cost	Leftover Material	Total Leftover Material	SKU#
2	252186		Mending Brace	Menards	36	N/A	Menards	\$0.98	1	\$35.28	N/A	N/A	2252186
22	250128		Corner Brace	Menards	58	N/A	Menards	\$0.89	1	\$51.62	N/A	N/A	2250128
4	1	1	Box Shelf										
4	2	1	Box Shelf Assembly/BOM	X	1	N/A	N/A	N/A	N/A	N/A	N/A	N/A	Assembly
4	3	1	Back Support	X	4	10.25 x 2.5 x 1.5	Menards	\$3.91	1	\$3.91	7x3x2	32x3x2	1110777
4	4	1	Back Board Support	X	1	80 x 5.25 x .50	Menards	\$17.79	1	\$17.79	80x18.75x.5	80x20.75x.5	1231456
4	5	1	Support Frame Bottom	X	5	5.25 x 1.5 x 1.5	Menards	\$3.37	1	\$3.37	9.75x2x2	151.75x2x2	1072416
4	6	1	Support Frame Top	X	5	5 x 1.5 x 1.5	Menards	\$0.00	0	\$0.00	-25x2x2	126.75x2x2	(Used from other wood)
4	7	1	Support Frame 45	X	5	5 x 1.5 x 1.5	Menards	\$3.37	1	\$3.37	11x2x2	137.75x2x2	1072416
4	8	1	Box Shelf Board	X	1	80 x 5 x .5	Menards	\$0.00	0	\$0.00	-80x5x.5	80x15.75x.5	(Used from other wood)
5	1	1	Push Piston Assembly										
5	2	1	Push Piston	x	2	40 x 4 x .5	Menards	\$0.00	0	\$0.00	2 (40 x 4 x .5)	0	1231456 (extra from box shelf)
5	3	1	Left Side C-Channel	X	4	3 x 3 x 6	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	4	1	Scissor Lift Bracket	X	40	5 x 1 x .25	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	5	1	right side c-channel	X	4	3 x 3 x 6	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	6	1	new linear acuator bracket	X	4	2.5 x 1 x 1.125	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	7	1	top push piston slider	X	4	5 x 2.5 x 1.5	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	8	1	push piston to table top bracket	X	8	9.25 x 3.5 x .25	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	9	1	linear acuator mountng bracket	X	8	8 x 3 x .25	In house	N/A	N/A	N/A	N/A	N/A	(We have It)
5	10	1	push piston slider	X	8	2.94 x 1.13	Mc-Master	N/A	N/A	N/A	N/A	N/A	Assembly

### Final Build Successes

- Assemblies
  - Tabletop
  - Base
  - Magnet & Sensors

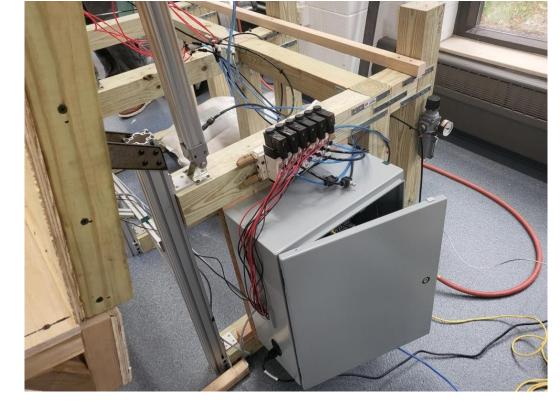


# **Final Build Complications**

- Linear actuator operation troubles
- High machining hours required for manufactured

parts

Miss-ordered parts



### **Final Build Gantt Chart**

Task name	Start date	End date	Assigned	Status	26.02.2024	28.02.2024	8	03.03.2024	05.03.2024	09.03.2024	11.03.2024	13.03.2024	15.03.2024	17.03.2024	19.03.2024	21.03.2024	25.03.2024	27.03.2024	29.03.2024	31.03.2024	02.04.2024	04.04.2024	08.04.2024	10.04.2024	12.04.2024	14.04.2024	16.04.2024	18.04.2024	20.04.2024	22.04.2024	26.04.2024	28.04.2024	30.04.2024	02.05.2024
Viracron Tilt Table	21.02.2024	03.05.2024	Jordan,Alex,Nate,Brandon,Sophie	In process																														
Collect Skews from Vendors	26.02.2024	01.03.2024	Jordan, Alex, Nate, Brandon	Closed																														
Complete Order Forms	01.03.2024	04.03.2024	Jordan,Alex,Nate,Brandon	Closed																														
Machine in house materials	22.03.2024	15.04.2024	Alex,Nate,Brandon	Closed																														
Laser cut material	09.04.2024	11.04.2024	Sophie	Closed																														
Assemble table base	08.04.2024	09.04.2024	Jordan,Alex,Brandon	Closed																														
Assemble tabletop	09.04.2024	10.04.2024	Jordan,Alex	Closed																														
Assemble Cart	11.04.2024	12.04.2024	Alex	Closed																														
Assemble Push Pistions	15.04.2024	18.04.2024	Jordan,Alex,Nate	Closed																														
Combine Assemblies	11.04.2024	18.04.2024	Alex,Nate	Closed																														
Create electrical box	18.04.2024	21.04.2024	Alex,Nate	Closed																														
Finalize controls	21.04.2024	22.04.2024	Alex,Nate	Closed																														
Trouble shoot controls	22.04.2024	26.04.2024	Alex,Nate	Closed																														
Demo Run	22.04.2024	26.04.2024	Alex,Nate	Closed																														
Create presentation	22.04.2024	26.04.2024	Jordan,Sophie,Brandon	Closed																														
Finish Binder	11.03.2024	03.05.2024	Jordan,Alex,Nate,Brandon,Sophie	In process																														

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# QUESTIONS?



# **APPENDIX**

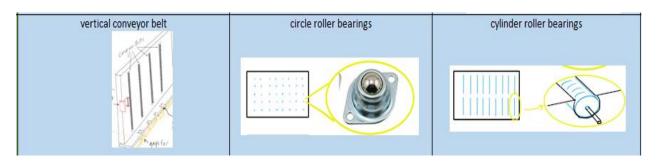
## **Appendix Links**

- A1 Design Concepts Semester 1
- A2 Predictive Analysis Semester 1
- A3 Controls Information Semester 1

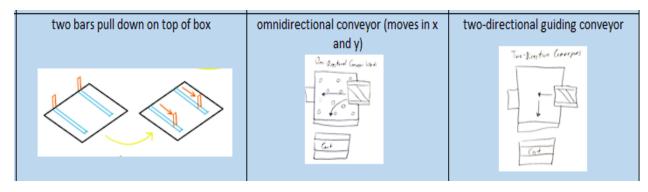
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# A1: DESIGN CONCEPTS SEMESTER 1

#### Functional Need – Align with The Bottom Shelf Prior to Lifting the Table

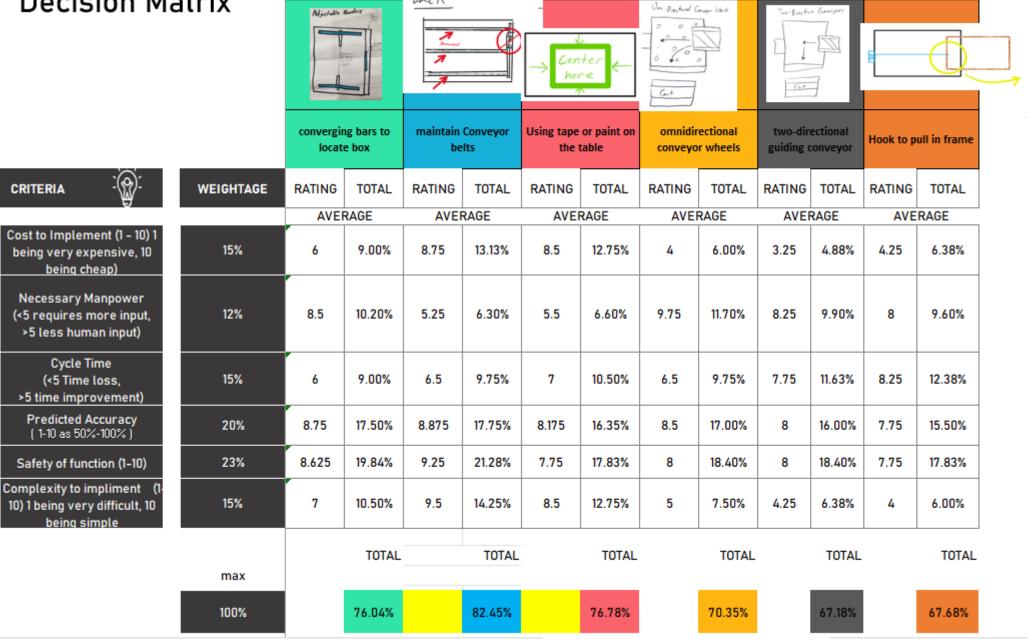


- Multiple designs were considered (Left).
  - Vertical conveyor belts
  - Roller bearings
  - Conveyor/pull bar contraptions
- A compromise was proposed by Viracon.
- Viracon will create a work instruction in place of a design solution.
  - Workers will orient box in line with the table's loading side before centering



#### Locating Box in the Center

#### **Decision Matrix**

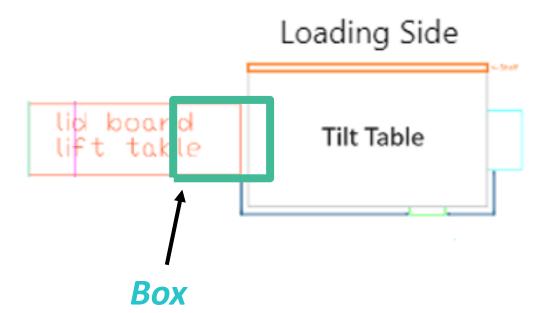


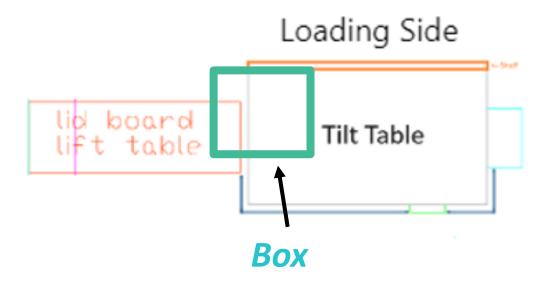
Back

# Demonstration Diagram

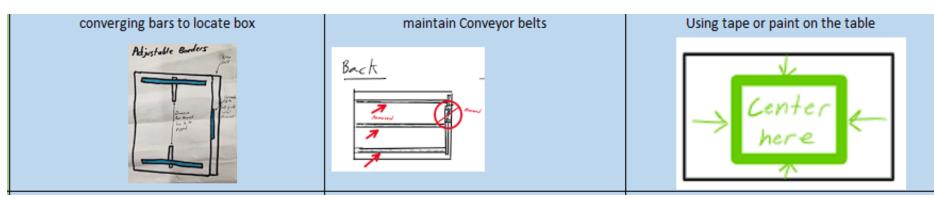
Box enters workspace on Lid table

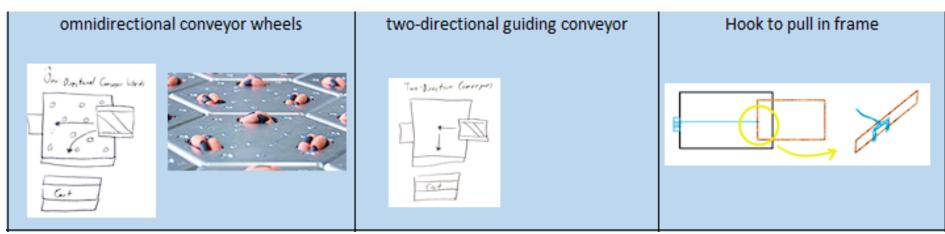
Box is oriented to have bottom edge in line with the tables loading side.





### Functional Need - Locate the box to the center of the table





#### Locating Box in the Center

### **Decision Matrix**

WEIGHTAGE

15%

12%

15%

20%

23%

15%

max

100%

CRITERIA

ost to implement (1 - 10)

1 being very expensive, 10 being cheap)

Necessary Manpower (<5 requires more input,

>5 less human input)

Cycle Time (<5 Time loss,

>5 time improvement)
Predicted Accuracy

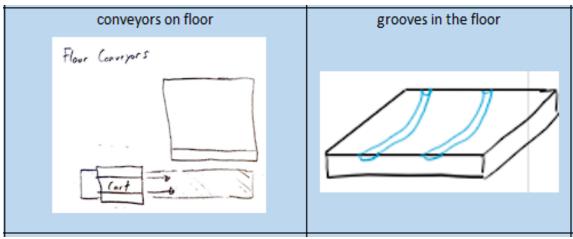
(1-10 as 50%-100%) Safety of function (1-10)

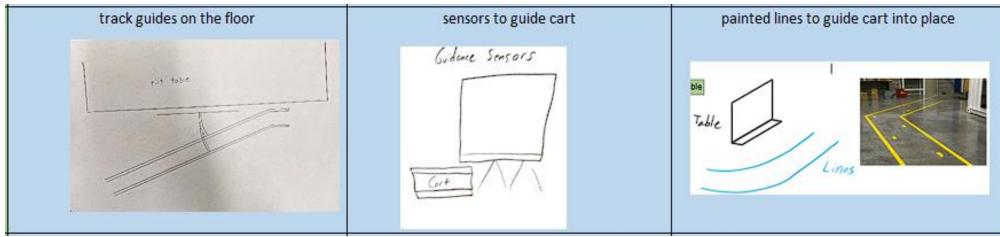
Complexity to impliment (1-10) 1 being very

difficult, 10 being simple

Alicelate andres		Back 2		→ Cen	ter re	On gant		Town-Bounds					
	converging bars to locate box		ntain or belts	_	tape or on the ble	omnidire conv whe		direct guid conv	tional	Hook to pull in frame			
RATING	TOTAL	RATING	TOTAL	RATING TOTAL		RATING	TOTAL	RATING	TOTAL	RATING	TOTAL		
AVE	RAGE	AVEF	RAGE	AVEF	RAGE	AVEF	RAGE	AVEF	RAGE	AVE	RAGE		
6	9.00%	8.75	13.13%	8.5	12.75%	4	6.00%	3.25	4.88%	4.25	6.38%		
8.5	10.20%	5.25	6.30%	5.5	6.60%	9.75	11.70%	8.25	9.90%	8	9.60%		
6	9.00%	6.5	9.75%	7	10.50%	6.5	9.75%	7.75	11.63%	8.25	12.38%		
8.75	17.50%	8.875	17.75%	8.175	16.35%	8.5	17.00%	8	16.00%	7.75	15.50%		
8.625	19.84%	9.25	21.28%	7.75	17.83%	8	18.40%	8	18.40%	7.75	17.83%		
7	10.50%	9.5	14.25%	8.5	12.75%	5	7.50%	4.25	6.38%	4	6.00%		
	TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		
	76.04%		82.45%		76.78%		70.35%		67.18%		67.68%		

### Functional Need – Move Cart into Repeatable Location Next to Tilt Table





9/2/2025

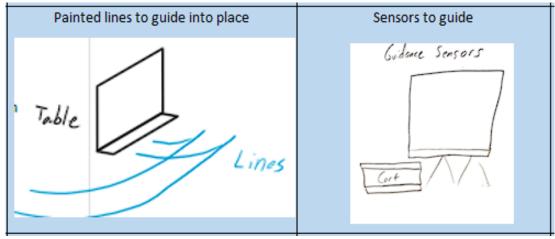
### Move Cart Into Location

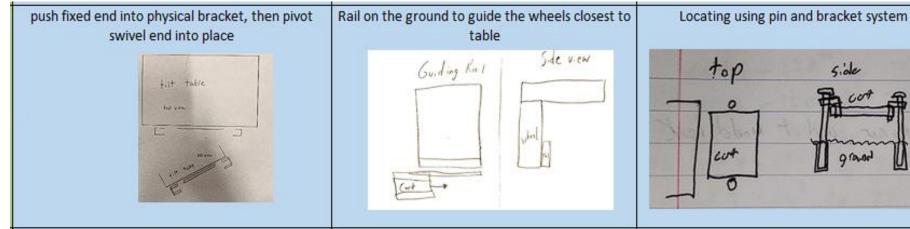
I)	eci	SI	on	Ma	itrix
	$\sim$ $\sim$	$\sim$ .	$\sim$		

				[ ]		u. D		Flow Compart	: 3				
		track gu the l		senso guide	ors to e cart	painted guide c pla	art into	convey		groove: flo	s in the		
CRITERIA -	WEIGHTAGE	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL		
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%	7.5	11.25%	7.25	10.88%	6.75	10.13%	1.75	2.63%	7.75	11.63%		
Necessary Manpower (<5 requires more input, >5 less human input)	12%	5.5	6.60%	5	6.00%	4.75	5.70%	5	6.00%	5	6.00%		
Cycle Time (<5 Time loss, >5 time improvement)	15%	5.25	7.88%	4.75	7.13%	5.75	8.63%	6.25	9.38%	5	7.50%		
Predicted Accuracy (1-10 as 50%-100%)	20%	9.75	19.50%	8	16.00%	5.75	11.50%	6	12.00%	8.75	17.50%		
Safety of function (1-10)	23%	4	9.20%	8.25	18.98%	6.5	14.95%	2.75	6.33%	4.25	9.78%		
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%	5.5	8.25%	7.5	11.25%	8.5	12.75%	4.75	7.13%	6	9.00%		
	max		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		
	100%		62.68%		70.23%		63.65%		43.45%		61.40%		

Gilare Sersors

### Functional Need – Repeatable Location of Cart for Loading Boxes





# Location of Cart For Loading

Decision Matrix

CRITERIA

Cost to Implement (1 - 10) 1 being very expensive,

10 being cheap) Necessary Manpower

(<5 requires more input,</p> >5 less human input) Cycle Time

(<5 Time loss, >5 time improvement) Predicted Accuracy

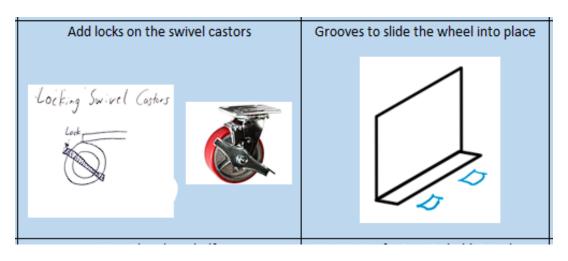
(1-10 as 50%-100%) Safety of function (1-10)

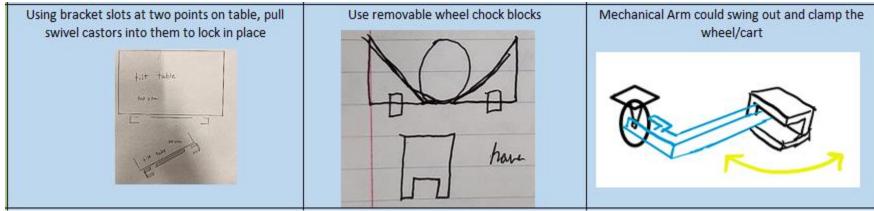
Complexity to impliment

(1-10) 1 being very difficult, 10 being simple

								Table	Lines			
		push fixed end into physical bracket, then pivot swivel end into place		Rail on the ground to guide the wheels closest to table		Locating using pin and bracket system				Sensors to guide		
ì	WEIGHTAGE							RATING	TOTAL	RATING	TOTAL	
		AVER	RAGE	AVEF	RAGE	AVEF	RAGE					
	15%	6	9.00%	7.5	11.25%	5.5	8.25%	9.25	13.88%	8	12.00%	
	12%	5.75	6.90%	5.5	6.60%	4.5	5.40%	5.25	6.30%	5.5	6.60%	
	15%	7.75	11.63%	6.5	9.75%	4	6.00%	5.75	8.63%	5.25	7.88%	
	20%	9.25	18.50%	7	14.00%	8.25	16.50%	6.25	12.50%	8.5	17.00%	
	23%	7.75	17.83%	6.5	14.95%	6.5	14.95%	6.75	15.53%	8.5	19.55%	
ĺ	15%	8.5	12.75%	8	12.00%	6.25	9.38%	8.5	12.75%	6.5	9.75%	
	max		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL	
	100%		76.60%		68.55%		60.48%		69.58%		72.78%	

### Functional Need – Repeatable Securing of Cart in Place

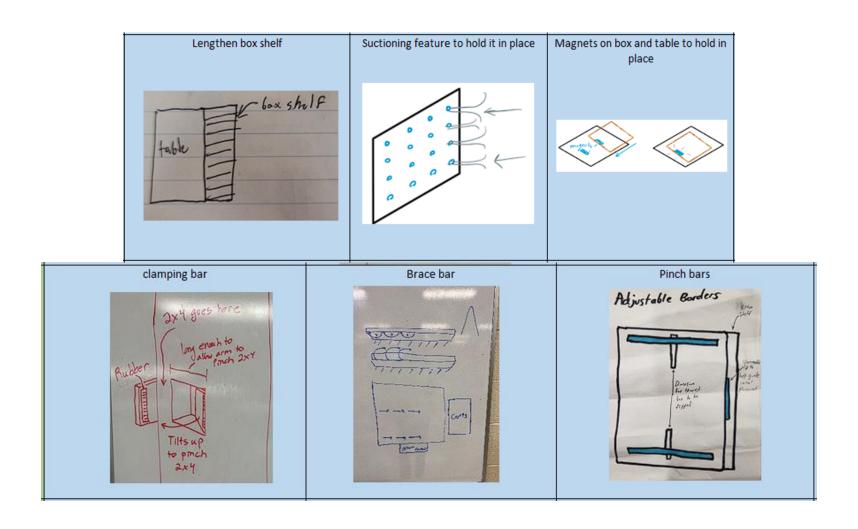




# Securing of Cart In Place Decision Matrix

	470 744 		To how		<b>O</b>		backing Servel Capity				
			oracket ots		novable chock cks	The second second second second second		Add lo the s cas	wivel	slide whee	res to the linto ice
CRITERIA	WEIGHTAGE	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL
		AVE	RAGE	AVE	RAGE	AVEF	RAGE		I		
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%	6.5	9.75%	7	10.50%	4.75	7.13%	7	10.50%	8	12.00%
Necessary Manpower (<5 requires more input, >5 less human input)	12%	6	7.20%	4.5	5.40%	5.75	6.90%	6	7.20%	4.75	5.70%
Cycle Time (<5 Time loss, >5 time improvement)	15%	7.75	11.63%	5	7.50%	5.5	8.25%	5.5	8.25%	5.25	7.88%
Predicted Accuracy (1-10 as 50%-100%)	20%	9.5	19.00%	7.5	15.00%	6.5	13.00%	5.75	11.50%	7.5	15.00%
Safety of function (1-10)	23%	8	18.40%	7.5	17.25%	6	13.80%	7.5	17.25%	5	11.50%
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%	8.5	12.75%	9	13.50%	4.5	6.75%	8.25	12.38%	6.75	10.13%
			TOTAL		TOTAL		TOTAL		TOTAL		TOTAL
	max	l									
	100%		78.73%		69.15%		55.83%		67.08%		62.20%

### Functional Need – Prevent Tipping of Box upon Lifting of Tilt Table

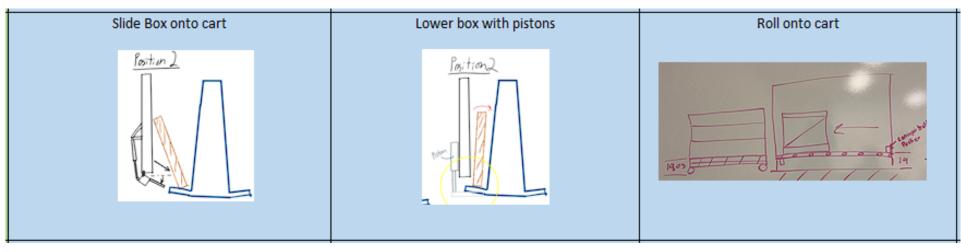


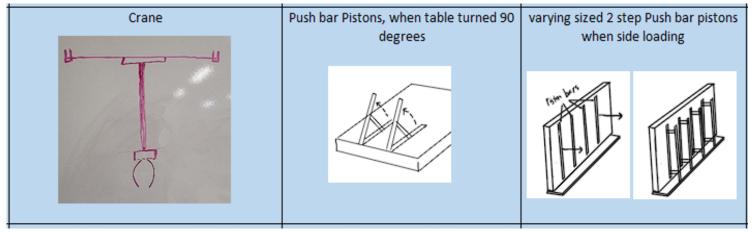
9/2/2025

**Prevent Tipping of Box** 

Decision M	- Inches	ing bar	Brace		Aljustate		lengthen	box shelf	feature	oning to hold n place	and on	s on box table to	
CRITERIA	WEIGHTAGE	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL
		AVEF	RAGE	AVEF	RAGE	AVEF	RAGE						
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%	5	7.50%	4.75	7.13%	4.25	6.38%	8.5	12.75%	3.5	5.25%	1.75	2.63%
Necessary Manpower (<5 requires more input, >5 less human input)	12%	10	12.00%	9.25	11.10%	8.75	10.50%	9	10.80%	9.5	11.40%	8.25	9.90%
Cycle Time (<5 Time loss, >5 time improvement)	15%	8.75	13.13%	7.5	11.25%	7.25	10.88%	6.75	10.13%	5	7.50%	7.25	10.88%
Predicted Accuracy (1-10 as 50%-100%)	20%	7.25	14.50%	7.5	15.00%	8.25	16.50%	8.5	17.00%	3.5	7.00%	5.5	11.00%
Safety of function (1-10)	23%	7.25	16.68%	8	18.40%	6.75	15.53%	8.75	20.13%	5.75	13.23%	4.5	10.35%
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%	4.25	6.38%	4	6.00%	5.25	7.88%	9.125	13.69%	4.25	6.38%	6.75	10.13%
	max		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL
	100%		70.18%		68.88%		67.65%		84.49%		50.75%		54.88%

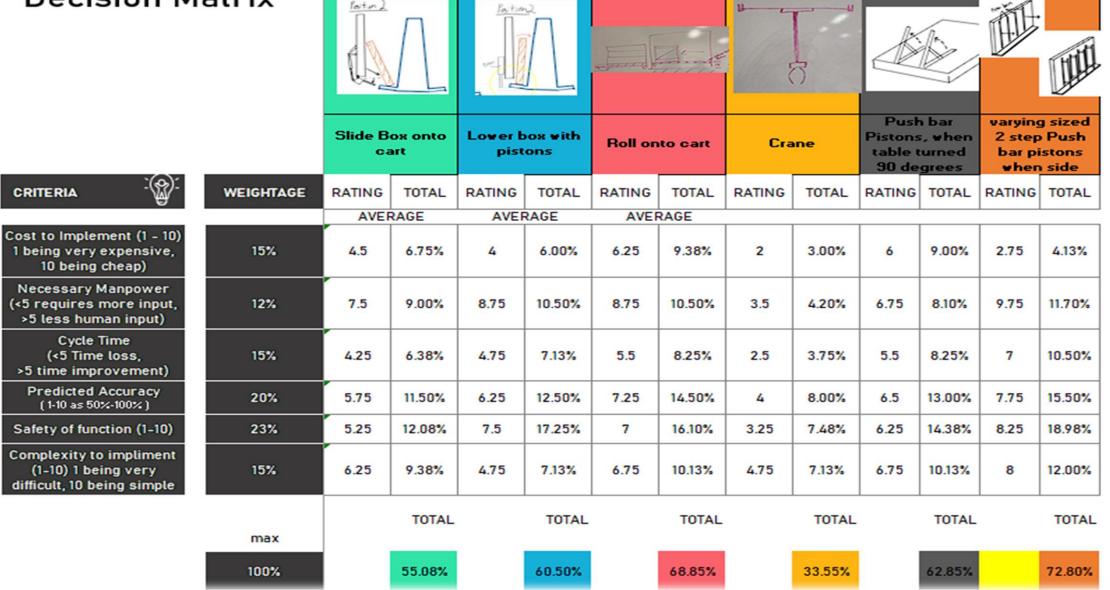
### Functional Need – Moving the Box from the Tilt Table to the Cart



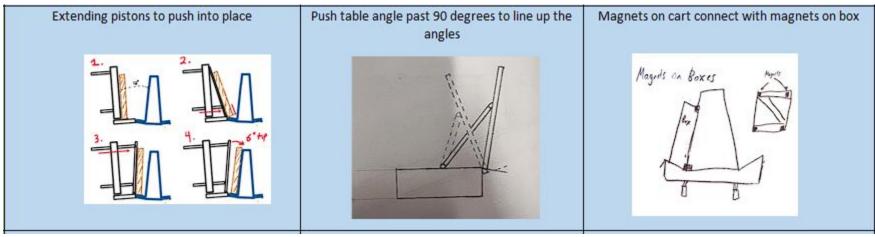


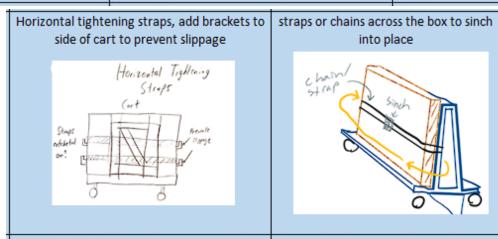
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### Tilt Table to The Cart Decision Matrix



### Functional Need – Ensuring the Box is Flush up against the Cart



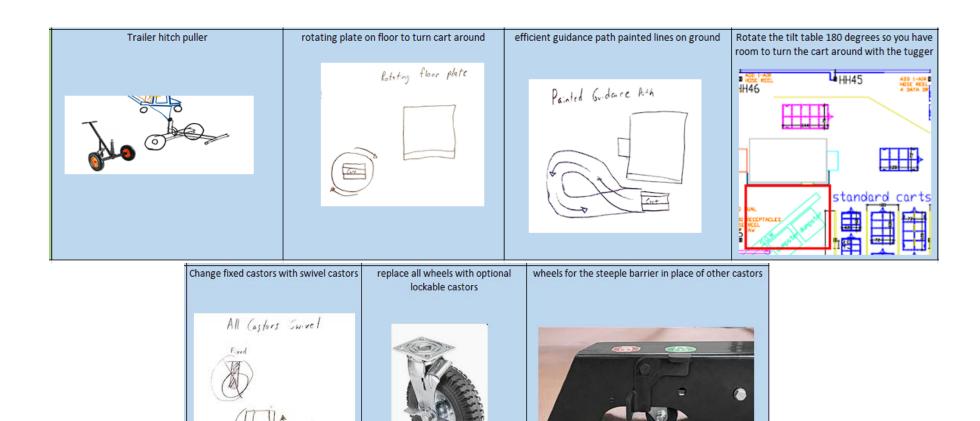


# Box Flush Up Against The Carts

**Decision Matrix** 

Decision Matrix						Royal in Buser		Hannahal Egilang		Charles of the control of the contro	
		Exter pistons into p	to push	degrees	past 90	Magnets connec magnets	ct with	tighte straps brackets of ca	ening s, add s to side art to	strap chains the b sinch pla	across ox to into
CRITERIA :	WEIGHTAGE	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL
		AVE	RAGE	AVE	RAGE	AVEF	RAGE				
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%	3.75	5.63%	9.25	13.88%	3	4.50%	7.5	11.25%	8	12.00%
Necessary Manpower (<5 requires more input, >5 less human input)	12%	9.75	11.70%	6.75	8.10%	5.5	6.60%	4.75	5.70%	4.5	5.40%
Cycle Time (<5 Time loss, >5 time improvement)	15%	5.75	8.63%	6	9.00%	4.75	7.13%	3.5	5.25%	3.5	5.25%
Predicted Accuracy (1-10 as 50%-100%)	20%	8	16.00%	7.875	15.75%	7	14.00%	6.25	12.50%	6.5	13.00%
Safety of function (1-10)	23%	7.5	17.25%	6.5	14.95%	7	16.10%	6.75	15.53%	6.25	14.38%
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%	4.25	6.38%	7.25	10.88%	8	12.00%	7.75	11.63%	6.75	10.13%
	max		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL
	100%		65.58%		72.55%		60.33%		61.85%		60.15%

### Functional Need – Ensure Safe Turn Around of Loaded Cart



9/2/2025

### Safe Turn Around of Loaded Cart

**Decision Matrix** 

Decision Matrix		also c		L.	ing law plate	Sm co	love Ara			(F)	The series of th	V			
		railer hitch on fl		on floor	loor to turn		ce path lines on und turn the cart around with the		so you oom to e cart	castors with swivel castors		optional		wheels for the steeple barrier in place of other castors	
CRITERIA	WEIGHTAGE	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL	RATING	TOTAL
		AVEF	RAGE	AVEF	RAGE	AVERAGE									
Cost to Implement (1 - 10) 1 being very expensive, 10 being cheap)	15%	7.25	10.88%	2.25	3.38%	9	13.50%	7	10.50%	5	7.50%	5.5	8.25%	3.25	4.88%
Necessary Manpower (<5 requires more input, >5 less human input)	12%	7	8.40%	8.25	9.90%	5.25	6.30%	5.5	6.60%	5.75	6.90%	5.25	6.30%	4.75	5.70%
Cycle Time (<5 Time loss, >5 time improvement)	15%	4.5	6.75%	7.5	11.25%	4.75	7.13%	5.5	8.25%	5.5	8.25%	6.25	9.38%	4.75	7.13%
Predicted Accuracy (1-10 as 50%-100%)	20%	5.75	11.50%	7	14.00%	5.5	11.00%	6.5	13.00%	6.5	13.00%	6.5	13.00%	6.75	13.50%
Safety of function (1-10)	23%	7	16.10%	5.75	13.23%	5.75	13.23%	6.75	15.53%	6.25	14.38%	7.25	16.68%	7.25	16.68%
Complexity to impliment (1-10) 1 being very difficult, 10 being simple	15%	7.5	11.25%	5.5	8.25%	7	10.50%	7	10.50%	7.25	10.88%	7.25	10.88%	6.25	9.38%
			TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL		TOTAL
	max									1					
	100%		64.88%		60.00%		61.65%		64.38%		60.90%		64.48%		57.25%

# A2: PREDICTIVE ANALYSIS SEMESTER 1

# Showstopper #1: Locating Cart in Loading Zone

What is the optimal distance from the cart to the table to accommodate all box depth sizes?	Hand Calculations/ experiment	Sponsor documentation of box shop layout	testing and experiment	modeling and sketch	This will inform us of the appropriate location for the cart that will accommodate all box sizes.
---	----------------------------------	---	------------------------	------------------------	---

- Max box depth = 24 inches
- Min Box depth = 4 inches
- Main Problem Center of gravity exceeds edge of box shelf and causes boxes to fall



## Calculations and proof

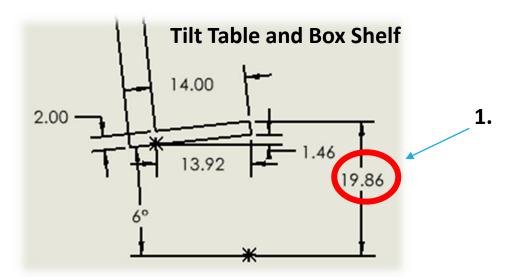
### **Explanation:**

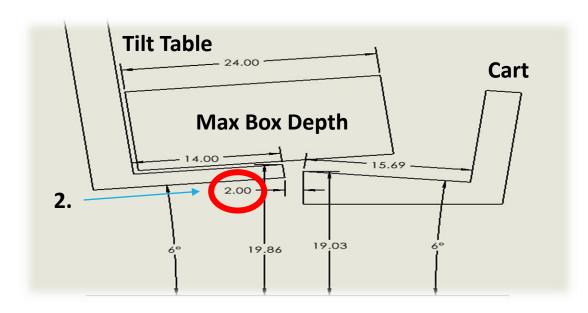
### Known

- Cart max height next to table = 19.03"
- Our Box shelf is 14" by 2"

### Unknown

- Height to increased shelf length
  - $\circ$  = 18.38+ 2"\*sin(6) + 14"\*sin(6) = 19.86"
- Shortest Center of Gravity = 4/2 = 2"
  - The Gap can be no greater than 2 inches to avoid the weight shift
- Next steps:
  - If this distance is determined to be too large, it can be shortened easily by moving the brace bar.







# Showstopper #2: Securing Cart for Loading

Are all 6 degrees of freedom locked when securing the cart?

Hand Calculations

Jigs and Fixtures Notes and resources

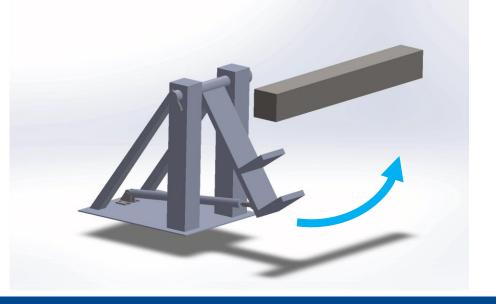
calculations and experiment

sketches

This will inform us if the cart is properly secured.

Design: Two pneumatically extending arms to clamp onto the lower portion of the cart frame



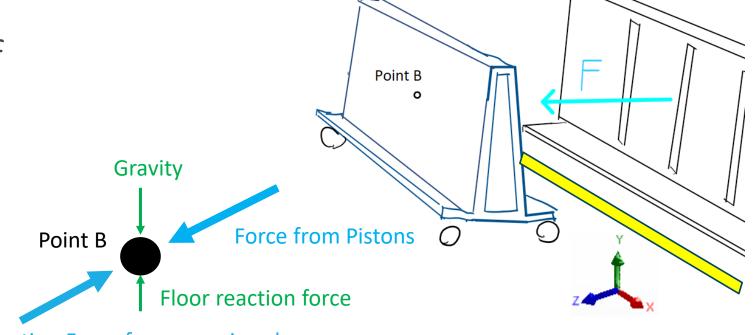




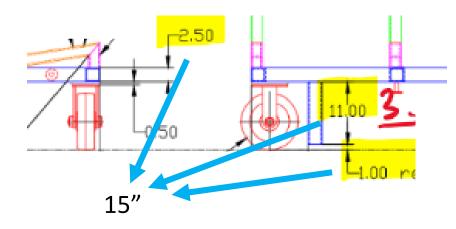
# Calculations and proof

### Explanation:

- Both the cart and clamp will be positioned directly next to the brace bar
- Pneumatically operated, triggered manually on the HMI.'
- Operation of Degrees of Freedom:
  - Y Axis: Locked by ground
  - X Axis: Locked by Clamp bar
  - Z Axis: Zero Force acts, so locking is unnecessary
- •The total height the clamp would have to reach to is: 2.5+11.0+1.0 = 14.5 inches
  - Model axle is located at this height. (Subject to being lowered if there is collision between this and the box shelf)

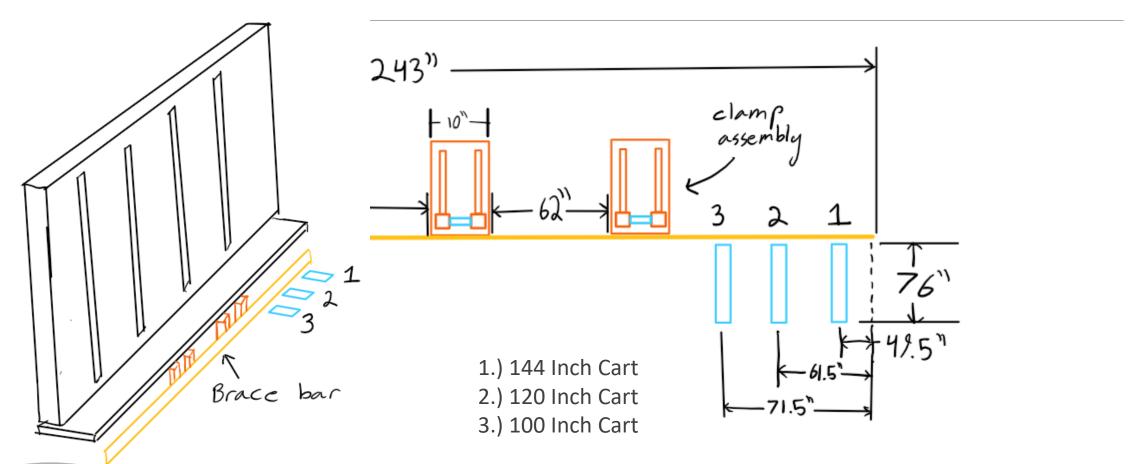


Reaction Force from securing clamp





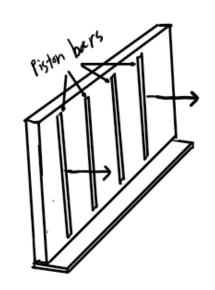
# Proof Continued...

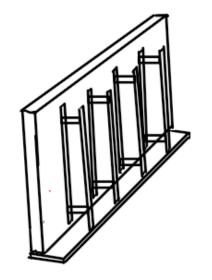


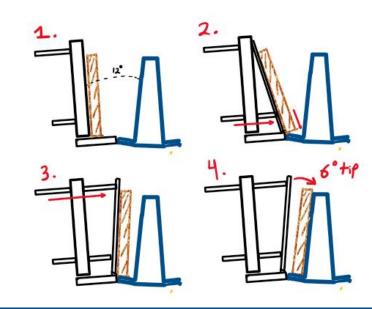


# Showstopper #3: Box is Flat against cart

How far do the This will help us Wooden blocks determine the top/bottom pistons need to Sizes of the matching furthest distance Physical each extend to Experiment cart, table, and experimentatio scaled down necessary that push the box sized of box, pistons need to box. n flush to the back table, and cart extend and piston of the cart? size.









### Calculations and proof

### **Explanation:**

### Knowns:

- Angle difference: 12 degrees
- Depth of box shelf: 14in
- Depth of deepest cart: 15.69in
- Smallest box depth: 4in

### Solved Values with AutoCAD:

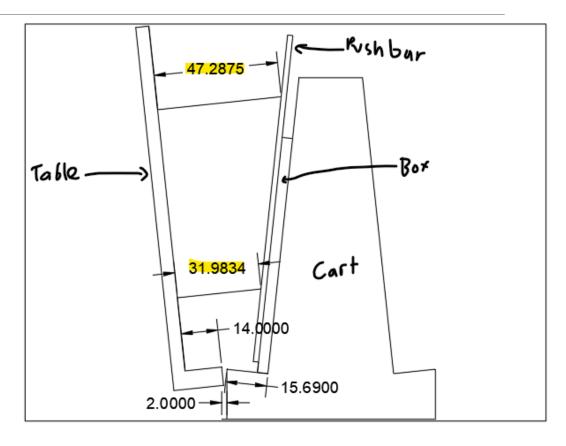
- Max extension for bottom piston: 31.984in
- Max extension for top piston: 47.2875in

### Assumed values:

- Distance between shelf and cart: 2in
- Vertical positions of pistons:24in from top and bottom

### Next steps:

- Complete in-depth comparison matrix for Hydraulic vs Pneumatic Pistons
- Piston lengths may be shorter if testing shows boxes naturally slide into position



# Showstopper #4:Lifting the Table

what is the force and pressure in the hydrulics to raise the table up to 84 degrees?

hand calculations

Specs on pistons used on curretn tilt table Sponsor infromation of box sizes, center of mass of boxes

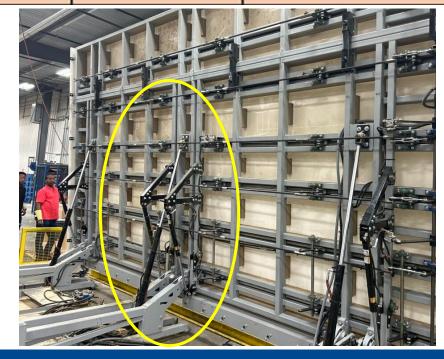
Models, solidworks simulation To inform us the amount of force and pressure is being excerted on the hydrulics.

### **Explanation:**

- Min weight increase: 4x Hydraulic Pistons: 5kg/11lbs each w/connections and hydraulic fluid = 80 lbs increased weight
- Weight of Box shelf change predicted to be negligible.
- Current pistons rated at 500 lb each, table current weight is

### Next steps:

- Continue calculating size requirements and weights of components as research provides.
- Are the current hydraulic pistons strong enough or do we need to order new ones?



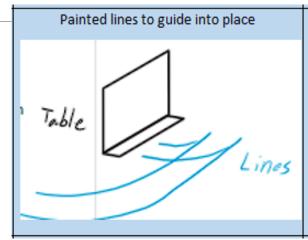
# Additional Supporting Data

### **Functional Need:**

- Painted lines to guide cart into location for loading:
  - Plan: Experiment during prototype phase for what the turn radius of the cart is. This would determine the distance away from the table to locate paint.



- For boxes causing force to move cart exceeding 100 lbs., dolly must be used to prevent potential injuries
- Dolley hitch will be adjusted to fit current method of pulling heavier carts.







# Material Choice Justifications - Prototype

- •Tabletop: Plywood Cheap and easy to manipulate for adjustments.
- ■Table structure: Combo of 4x4 and 2x4 wood.
- Box Shelf and push piston bar: HDPE Self lubricating material for low coefficient of friction for good price.
- Shelf structure, ground brace bar and cart clamp structure:
   2x4 wood Strong enough to hold high weight, cheap in cost.
- Small scale cart: Aluminum square stock and miniature castor wheels.
- •Small scale Box: plywood and 2x4 wood cut to size w/ extra weight for realism.



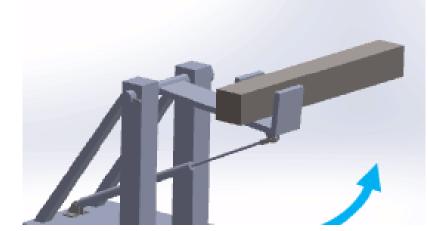


# Potential Design, Manufacturing or Process Issues

- 1. The box may shift in a way where the lower end of the push bars pass through the center of the box.
  - This may be solved by requiring boxes to have at least one crossframe support and to be oriented, so the support is perpendicular to push bars.



- 2. Will the clamp arms reliably close tightly enough around the cart frame for securing?
  - This could be solved by elevating the brace bar and requiring the cart to be flat against it. This way the clamp arms can be reduced to a shorter length and will be more consistent.



# A3: CONTROLS INFORMATION SEMESTER 1

# Inputs

Outputs

PB1- Estop (N.C.)

PB2- Home (N.O.)

PB3- Conveyors Raising (N.O.)

LS1- Box Shelf Fully Extend

LS2- Box Shelf Fully Retracted

LS3- Tilt Table Fully Extended

LS4 – Tilt Table Fully Retracted

LS5 – Bottom Piston Fully Extend

LS6- Bottom Piston Fully Retraced

LS7- Bottom Piston Force Detection

LS8 – Top Piston Fully Extend

LS9- Top Piston Full Retraced

LS10- Top Piston Force Detection

LS11- Secure Cart Fully Extend

LS12- Secure Cart Fully Retraced

M1- Hydraulic Pump

M2- Pneumatic Pump

M3 – Conveyor Motor

Sol 1- Conveyors Ext/Ret

Sol 2- Tilt Table Ext/Ret

Sol 3- Box Shelf Ext/ Ret

Sol 4- Secure Clamp Ext/Ret

Sol 5- Top Piton Ext/Ret

Sol 6- Bottom Piston

Ext/Ret



### (Loading of the 1st and 2nd Box on the A-Frame cart \*Tilt Table\*)

- 1. The cart is brought in to loading area by hand.
- The fixed wheel end will go in first with the Trailer Hitch, then the cart will be manual be pushed so it's lined up with the paint on the ground in center of table for that certain sized cart (3 different sizes)
- Once the cart is in place the operator will switch LS7 and will activate M3 and Sol 4 where it will raise the securing method to lock the cart.
- Once the box is done loading from the Tilt Table to A-Frame Cart, the operator will then switch LS7 and deactivate M3 and Sol 4 to lower the securing method.
- 5. The cart is then turned around and lined up on the same painted line in center of table.
- Then repeat Step 3-4
- 7. The cart is then brought out of loading area by the Buggy.
- 8. New cart is brought in to loading area and steps 1-7 are repeated.

### (Operation of the Box to the Green Ramp)

- 1. When the box is finished, it will stay in the middle of the table.
- All Conveyers will go up with the push and hold of PB3 and it will active Sol 1 it will grab the box to move towards the Green Ramp
- All Conveyers will be switched on by LS4 to start M1 and begin to go forward to the end of the table
- Once at the end switch LS4 off to stop the M1.
- 5. Then, all conveyors will go down with the release of PB3 and it will deactivate Sol 1.

# Operators Manual

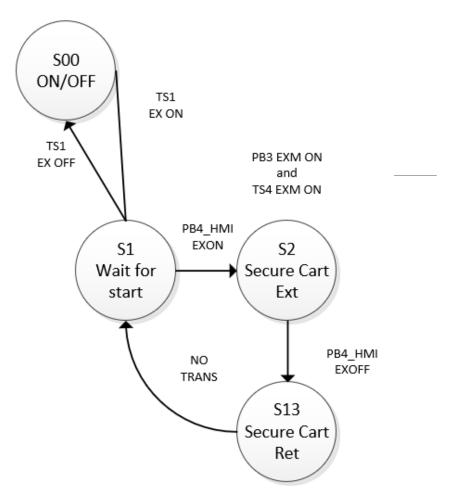
### (Operation of the Box on the Tilt Table)

- 6. When box is finished, they will have Work Instructions to place down flush to the Box Shelf.
- Next, all Conveyers will go up with the push and hold of PB3 and it will active Sol 1 it will grab the box to move towards center.
- All Conveyers will be switched on by LS4 to start the M1 and begin to go forward to the center of the table.
- If the box has gone too far from the center, switch off LS4 and use switch LS5 to reverse the M1 on the conveyors.
- 10. Once centered switch either LS4 or LS5 off to shut off M1
- 11. Then, all conveyors will go down with the release of PB3 and it will deactivate Sol 1.
- 12. The box shelf will then come up with switch LS7 and active Sol 3
- 13. Next, switch LS6 to active Sol 2 and the Tilt Table will go up to the 84 degrees.
- 14. Once at the 84 degrees, the switch LS2 will active Sol 6 and the bottom push piston will extend until a certain pressure is exerted and will stop its motion.
  - a. We will have the push piston back off 2 inches to allow space from box.
- 15. The top push piston will then begin to extend with switch LS3 and will active Sol 5 until a certain pressure is exerted and will stop its motion.
  - Unless the push piston reaches a max length at that point the box should be flush on the cart
- 16. As the push pistons are done with the action switch LS2 and LS3 will be turned off to deactivate Sol 5 and Sol 6 until they are retracted back into place.
- 17. As step #16 is going, switch LS6 and that will deactivate Sol 2 and the table will be lowered down to the 0-degree angle.
- Then the switch LS7 and that will deactivate Sol 3 that will retract the box shelf to its original position.



### (Loading of the 1st and 2nd Box on the A-Frame cart \*Tilt Table\*)

- 1. The cart is brought in to loading area by hand.
- 2. The fixed wheel end will go in first with the Trailer Hitch, then the cart will be manual be pushed so it's lined up with the paint on the ground in center of table for that certain sized cart (3 different sizes)
- 3. Once the cart is in place the operator will switch LS7 and will activate M3 and Sol 4 where it will raise the securing method to lock the cart.
- 4. Once the box is done loading from the Tilt Table to A-Frame Cart, the operator will then switch LS7 and deactivate M3 and Sol 4 to lower the securing method.
- 5. The cart is then turned around and lined up on the same painted line in center of table.
- Then repeat Step 3-4
- 7. The cart is then brought out of loading area by the Buggy.
- 8. New cart is brought in to loading area and steps 1-7 are repeated.

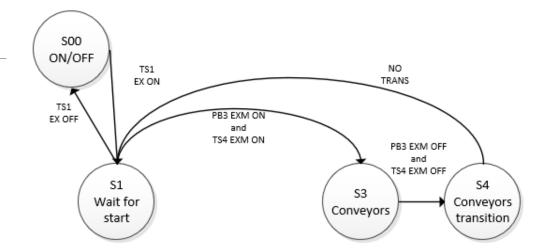


# Statement of Operations



### (Operation of the Box to the Green Ramp)

- 1. When the box is finished, it will stay in the middle of the table.
- 2. All Conveyers will go up with the push and hold of **PB3** and it will active **Sol 1** it will grab the box to move towards the Green Ramp
- 3. All Conveyers will be switched on by LS4 to start M1 and begin to go forward to the end of the table
- 4. Once at the end switch LS4 off to stop the M1.
- 5. Then, all conveyors will go down with the release of PB3 and it will deactivate Sol 1.

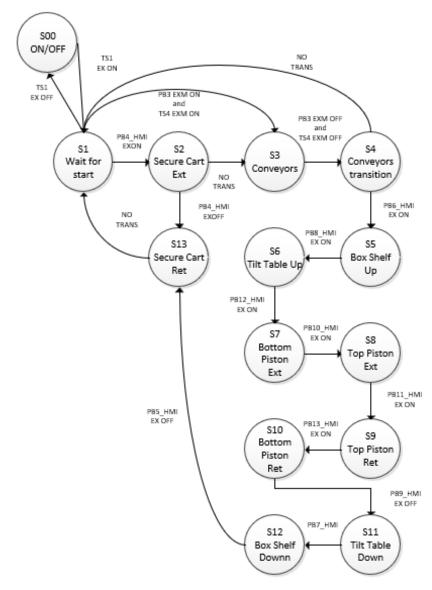


# Green Ramp Cycle

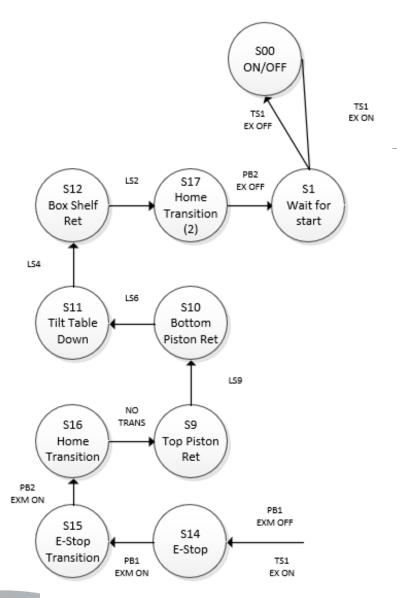


### (Operation of the Box on the Tilt Table)

- 6. When box is finished, they will have Work Instructions to place down flush to the Box Shelf.
- 7. Next, all Conveyers will go up with the push and hold of PB3 and it will active Sol 1 it will grab the box to move towards center.
- All Conveyers will be switched on by LS4 to start the M1 and begin to go forward to the center of the table.
- If the box has gone too far from the center, switch off LS4 and use switch LS5 to reverse the M1 on the conveyors.
- 10. Once centered switch either LS4 or LS5 off to shut off M1
- 11. Then, all conveyors will go down with the release of PB3 and it will deactivate Sol 1.
- 12. The box shelf will then come up with switch LS7 and active Sol 3
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  - a. We will have the push piston back off 2 inches to allow space from box.
- 15. The top push piston will then begin to extend with switch LS3 and will active Sol 5 until a certain pressure is exerted and will stop its motion.
  - Unless the push piston reaches a max length at that point the box should be flush on the cart
- 16. As the push pistons are done with the action switch LS2 and LS3 will be turned off to deactivate Sol 5 and Sol 6 until they are retracted back into place.
- 17. As step #16 is going, switch LS6 and that will deactivate Sol 2 and the table will be lowered down to the 0-degree angle.
- 18. Then the switch LS7 and that will deactivate Sol 3 that will retract the box shelf to its original position.

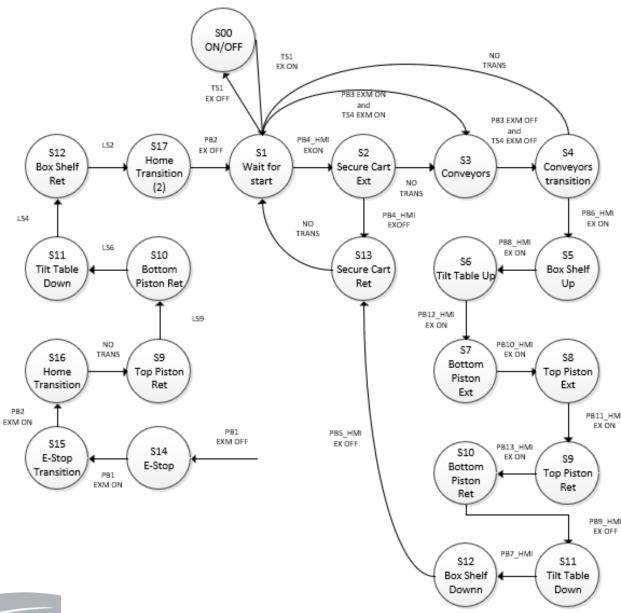


Statement of Operations Cont.

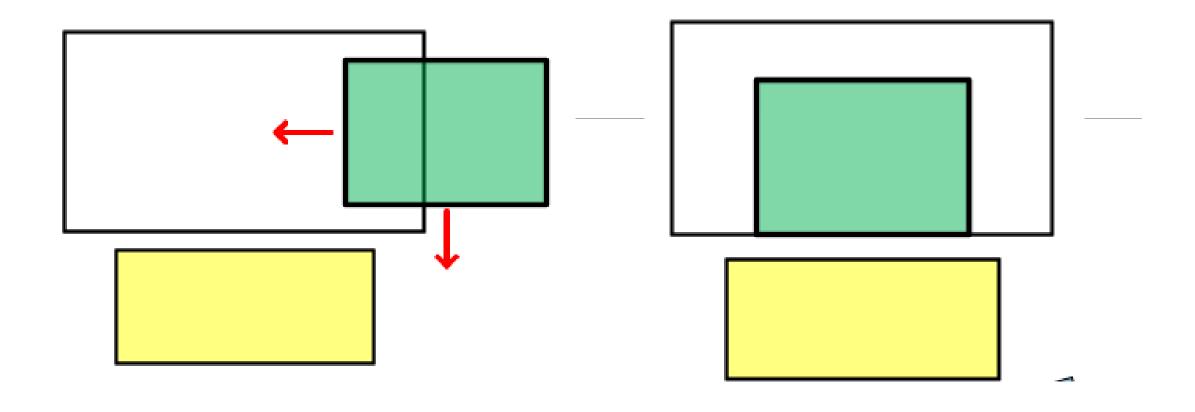


# Homing Cycle



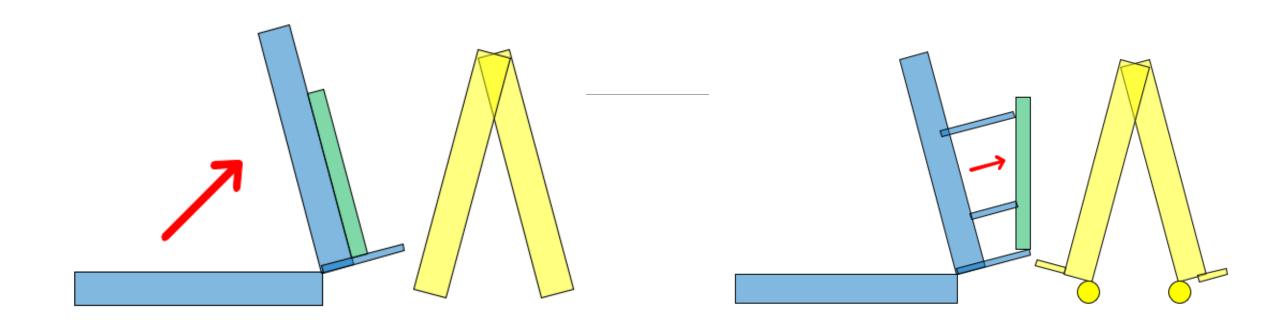


# State diagram



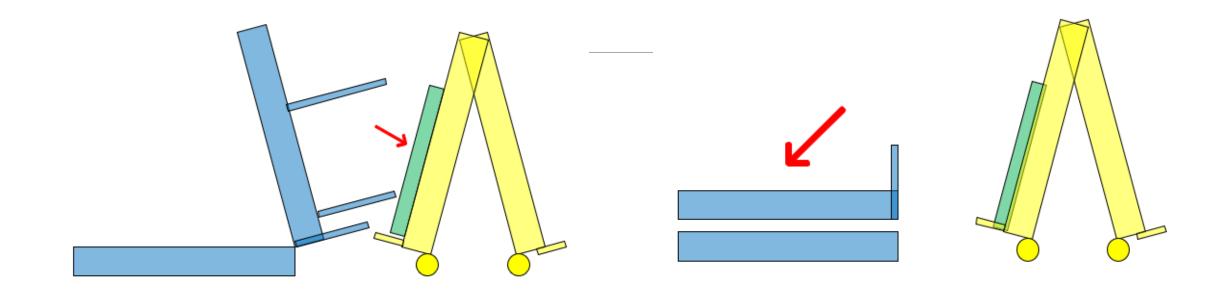
# Part Flow





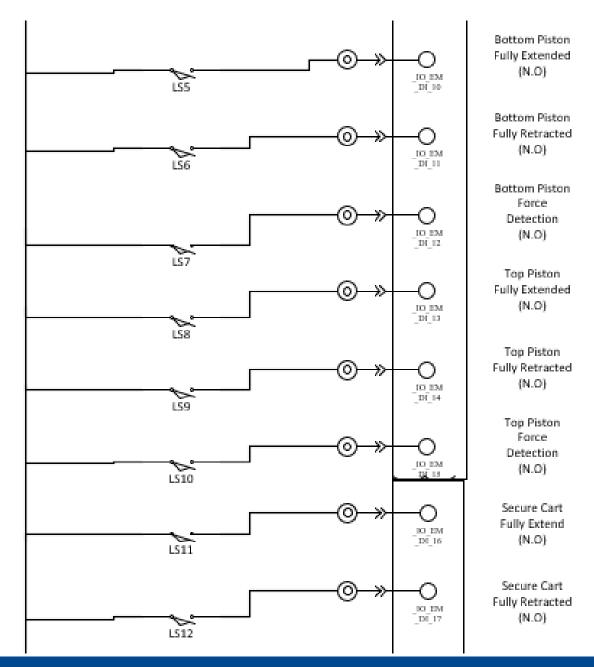
# Part Flow





# Part Flow







Short Device Name	CCW Variables	Full Description			
PB1	_IO_EM_DI_00	E-Stop (N.C.)			
PB2	_IO_EM_DI_01	Home (N.O.)			
PB3	_IO_EM_DI_02	Conveyors (N.O.)			
TS1	_IO_EM_DI_03	ON/OFF			
TS2	_IO_EM_DI_04	Conveyor Forward			
TS3	_IO_EM_DI_05	Conveyors reverse			
LS1	_IO_EM_DI_06	Box Shelf Fully Extend			
LS2	_IO_EM_DI_07	Box Shelf Fully retracted			
LS3	_IO_EM_DI_08	Tilt Table Fully Extend			
LS4	_IO_EM_DI_09	Tilt Table Fully Retracted			
LS5	_IO_EM_DI_10	Bottom Piston Fully Extend			
LS6	_IO_EM_DI_11	Bottom Piston Fully Retracted			
LS7	_IO_EM_DI_12	Bottom Piston Force Detection Reached			
LS8	_IO_EM_DI_13	Top Piston Fully Extend			
LS9	_IO_EM_DI_14	Top Piston Fully Retracted			
LS10	_IO_EM_DI_15	Top Piston Force Detection Reached			
LS11	_IO_EM_DI_16	Secure Cart Fully Extend			
LS12	_IO_EM_DI_17	Secure Cart Fully Retracted			

# Tag Table Inputs



Secure Cart	Secure Cart Extend				
Extend	Secure cont Exterior				
Secure Cart Retract	Secure Cart Retract	Secure Cart Retract			
Box Shelf Up	Box Shelf Up	Box Shelf Up			
Box Shelf Down	Box Shelf Down	Box Shelf Down			
Tilt Table Up	Tilt Table Up	Tilt Table Up			
Tilt Table Down	Tilt Table Down	Tilt Table Down			
Bottom Piston Extend	Bottom Piston Extend	Bottom Piston Extend			
Bottom Piston Retract	Bottom Piston Retract	Bottom Piston Retract			
Top Piston Extend	Top Piston Extend	Top Piston Extend			
Top Piston Retract	Top Piston Retract	Top Piston Retract			
Display to show angle	Display to show angle	Display to show angle			
Conveyors Up	Conveyors Up	Conveyors Up			
Conveyors Forward/ Reverse	Conveyors Forward/ Reverse	Conveyors Forward/ Reverse			
Run Mode	Run Mode	Run Mode			
Manual Mode	Manual Mode	Manual Mode			
Error Codes	Error Codes	Error Codes			

# HMI Tags



M1	_IO_EM_DO_00	Hydraulic Pump
M2	_IO_EM_DO_01	Pneumatic Pump
M3	_IO_EM_DO_02	Conveyor Motor
Sol1	_IO_EM_DO_03	Conveyors Ext/Ret
Sol2	_IO_EM_DO_04	Tilt Table Ext/Ret
Sol3	_IO_EM_DO_05	Box Shelf Ext/Ret
Sol4	_IO_EM_DO_06	Secure Clamp Ext/Ret
Sol5	_IO_EM_DO_07	Top Piston Ext/Ret
Sol6	_IO_EM_DO_08	Bottom Piston Ext/Ret

### Tag Table Outputs

S00	ON/OFF
S 1	Wait for Start
S 2	Secure Cart into Place
S 3	Conveyors Raise
\$4	Conveyors Transition
S 5	Box Shelf Raise
S6	Tilt Table Raise
\$7	Bottom Pistons Extend
\$8	Top Pistons Extend
S 9	Top Pistons Retract
S 10	Bottom Pistons Retract
S 11	Tilt Table Lower
S 12	Box Shelf Retract
S13	Secure Cart Release
\$14	E-Stop
\$15	E-Stop Transition
\$16	Home Transition
\$17	Home Transition (2)





State	SOL 1 Conveyors	SOL 2 Tilt table od/ret	SOL 3 Bax shelf ext/ret	SOL 4 Secure Clamp Ext/Ret	SOL 5 Top Piston Ext/Ret	SOL 6  Bottom Piston Ext/Ret	M1 Hydraulic pump	M2 Pneumati c pump	M3 Conveyor Motor4
S1									
S2				х				х	
S3	х			х			Х	х	х
S4				х			Х	х	
S5			х	х			Х	х	
S6		х	х	х			Х	х	
S7		х	х	Х		х	Х	Х	
S8		х	х	Х	х	х	Х	Х	
S9		х	х	х		х	Х	х	
S10		х	х	х			Х	х	
S11			х	Х			Х	х	
S12				Х				Х	
S13									
S14									
S15									
S16									
S17									

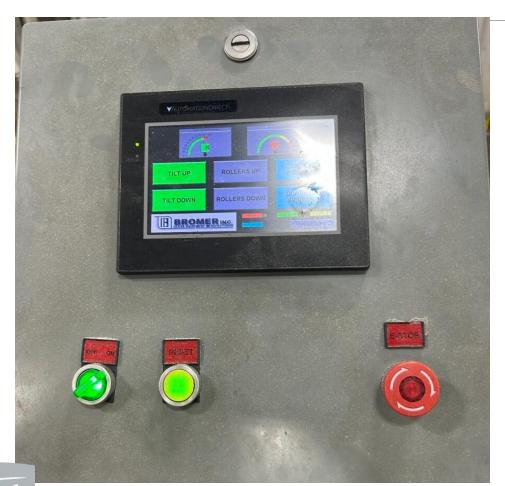
# State Output Table

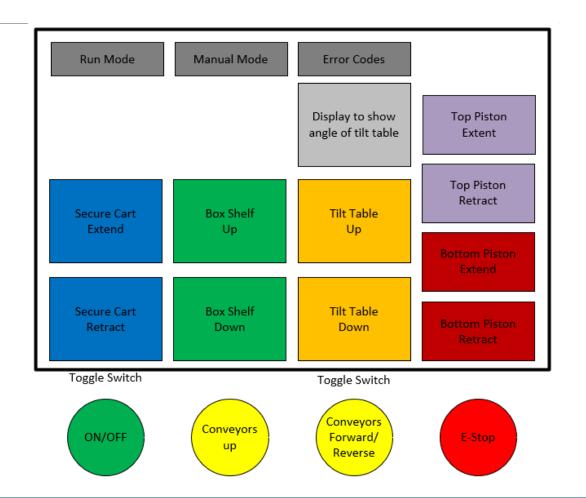


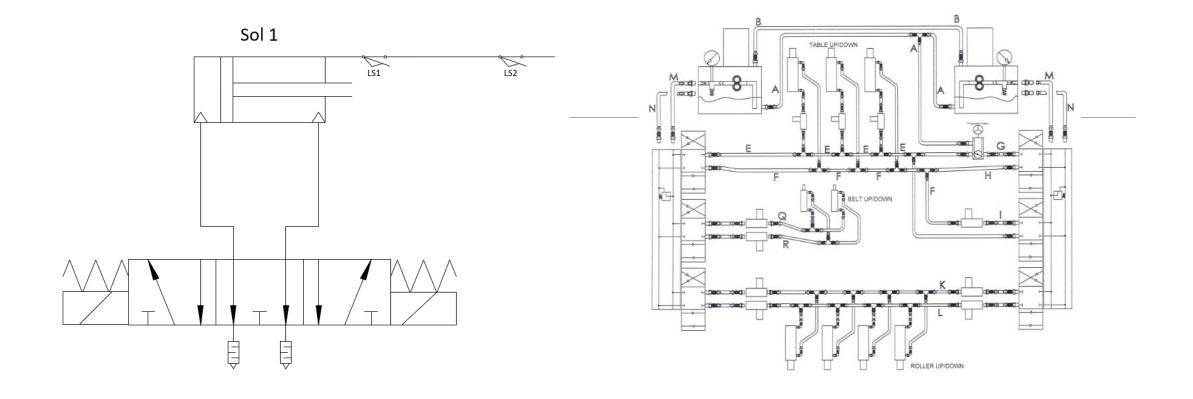




### HMI







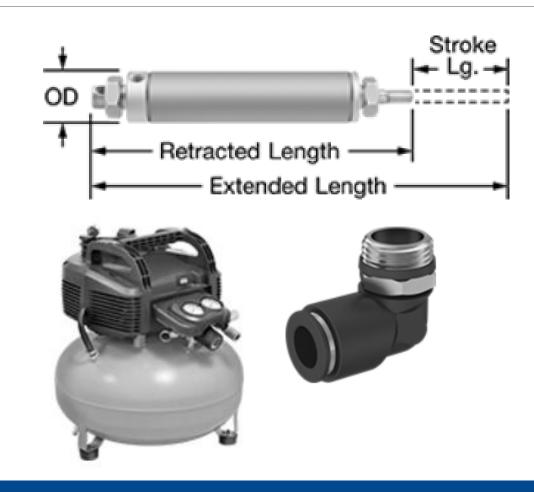
### Pneumatic Diagram



# Physical Components Required for the System

### Pneumatics

- Air Compressor
- 3x for raising up/down tilt table
- 4x extending and retracting box shelf
- 4 pneumatic pistons for push pistons
- 1x for raising and lowing conveyors
- Hoses
- Fittings
- Connectors



# Physical Components Required for the System

### **Motors**

• 120V AC Motors for conveyors



### Parts- Prototype

#### **ITEM NUMBERS**

- Festo
  - DNU-32-400-PPV-A
  - DNU-32-320-PPV-A



### **Prototype Solution Cost - Overview**

- Tilt Table Assembly -----\$1,787.82
- Tabletop -----\$109.10
- Bottom Frame -----\$751.97
- Box Shelf -----\$28.44
- Push Piston Assembly ---\$1,655.19
- Cart Connection -----\$926.47
- Cart Model -----\$329.73
- Total -----\$5,588.71

## **TEAMWORK**



### Teamwork

The first step of the process was establishing the team by establishing:

- The Goal
- Our Values
- Conflict Resolution
- Who We Are
- Ground Rules
- Additionally: Interim and End of Semester Peer Reviews

